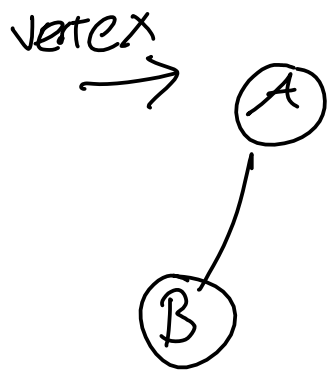


Graph = pair of two sets V and E
 \uparrow vertices \uparrow edges



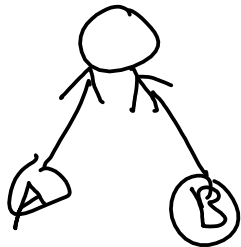
A and B are adjacent

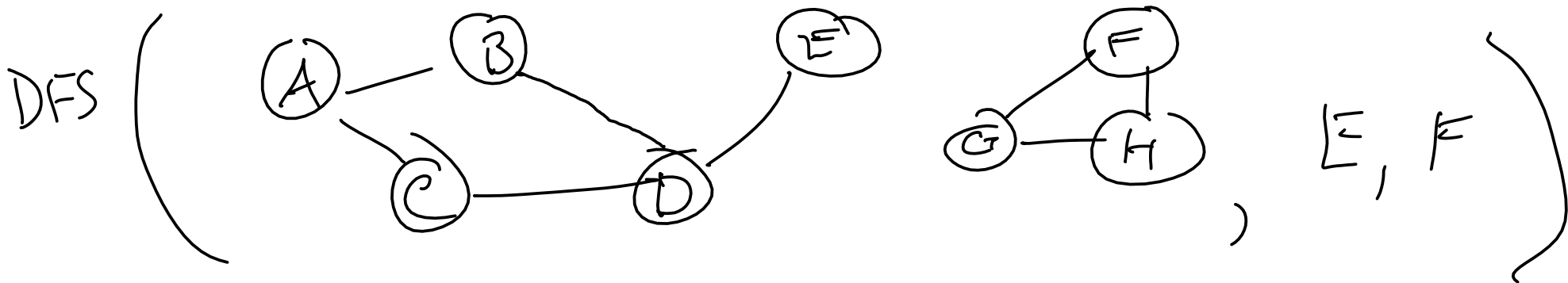
$$\langle A, B \rangle \approx \langle B, A \rangle$$

pair of vertices

defn. \rightarrow directed / undirected
 $\langle V, V, W \rangle \rightarrow$ weighted / unweighted

emergent \rightarrow connected: all vertices have some seq. edges that relate them





Function DFS (graph, start, end)

s ← new stack

s.push(start)

visited ← new Hash Table

visited.put(start, ...)

while stack not empty:

ns ← find_neighbors(s.pop(), graph) {A, B, C, D, E}

for each n in ns:

if n not a key in visited:

Return false

s.push(n)

visited.put(n, ?)

if n = end:

return True

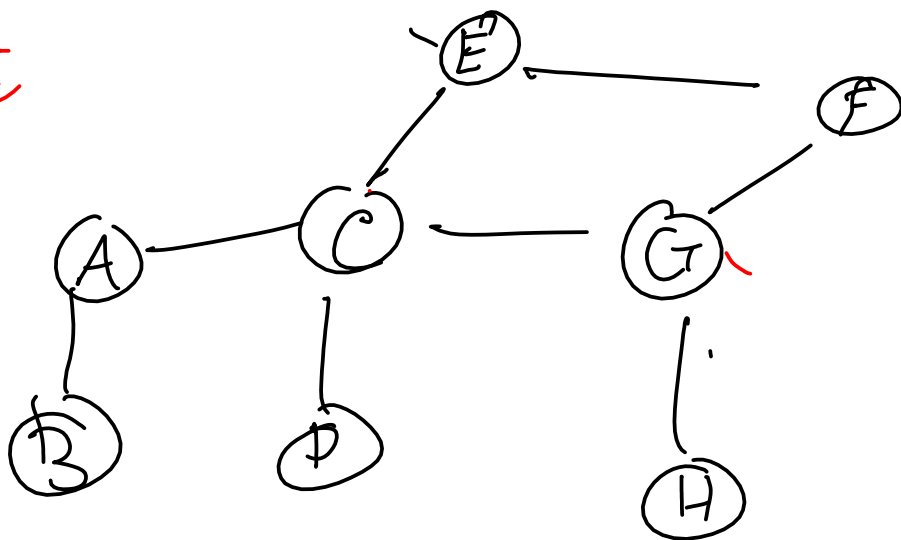
Function BFS (graph, start, end):

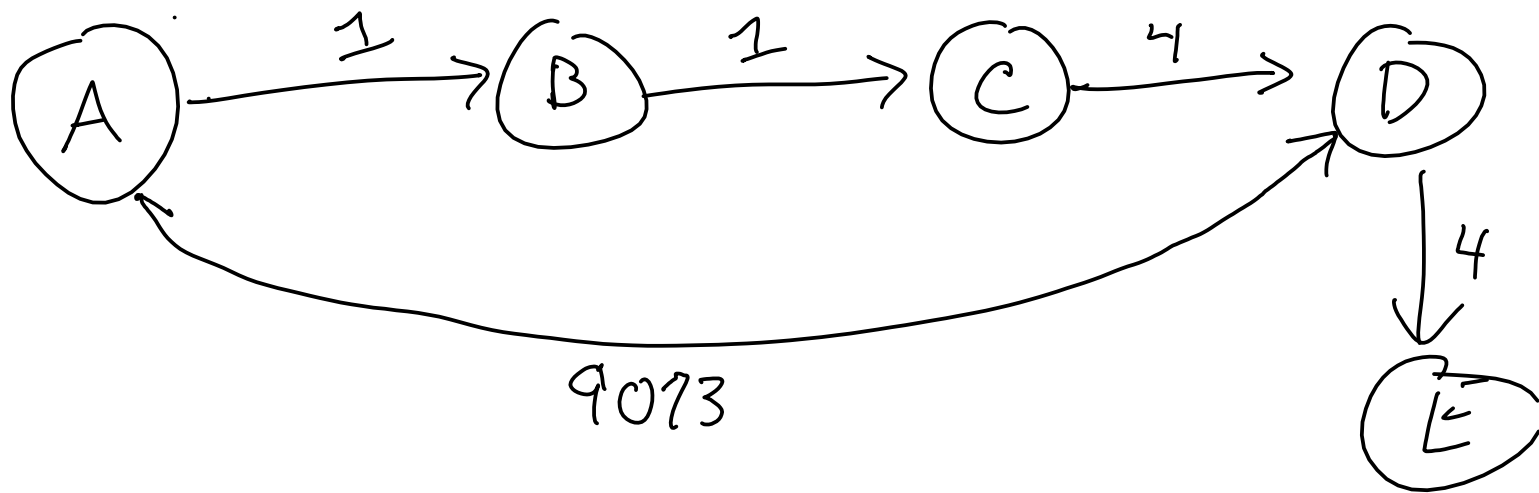
Like DFS but with queue

BFS: unweighted graph: guaranteed to give path w/ fewest edges

A \rightsquigarrow G

C/B
E/D/G
F/H





Right here is where lecture got really confusing. Instead of giving you the clunky, bad version of Dijkstra's Algorithm from class, we'll just go over it on Tuesday in a (hopefully clearer) fashion