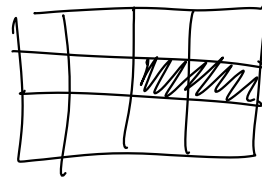
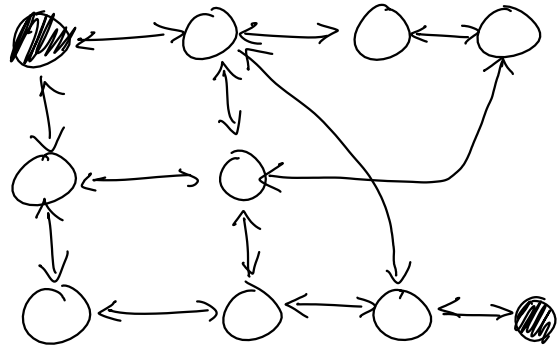


Graph Algorithms

Graph: $\langle V, E \rangle$

Edge: $\langle V, V, W, L \rangle$
src dst weight label



4 Graph Algorithms

- For Lab 9
- * reachable DFS (last week)
 - * shortestLengthPath BFS
 - * all Lengths Paths BFS
 - * singleSourceShortestPath (Dijkstra's)

Function shortestLengthPathBFS(graph, src, dst): list of vertices

frontier ← new Queue<V>

frontier.insert(src)

prev ← new Dictionary<V, V>

prev.insert(src, src)

} Initializing frontier

} Initializing accounting

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|E| is $O(|V|^2)$

While frontier is not empty:

current ← frontier.remove()

If current == dst:

cursor ← current
path ← new List

} Complete

path.insertFirst(current)

While cursor ≠ prev.get(cursor):

cursor ← prev.get(cursor)
path.insertFirst(cursor)

Return path

$O(|V|)$

$O(|V|)$

For neighbor In graph.getNeighbors(current):

If not prev.contains(neighbor):

prev.insert(neighbor, current)

frontier.insert(neighbor)

} Explore

$O(|E|)$

EndIf

EndFor

EndWhile

$O(|V|^2)$

||
(

Function allLengthsBFS(graph, src) : Dictionary <V, int>

frontier ← new Queue <V>

frontier.insert(src)

length ← new Dictionary <V, int>

length.insert(src, 0)

While frontier is not empty:

current ← frontier.remove()

For each neighbor of current:

If not length.contains(neighbor):

length.insert(neighbor, length.get(current) + 1)

frontier.insert(neighbor)

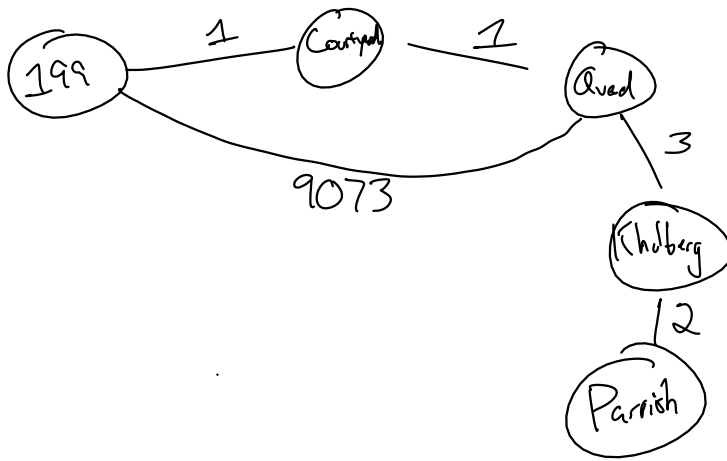
EndWhile

Return length

EndFunction

↙ # of edges

$O(|E|)$



Function SSSP(graph, src) : Dictionary < V, int > ^{total cost}

frontier ← new PQ < int, V > ← low priority is next
 frontier.insert(0, src)

cost ← new Dictionary < V, int >
 cost.insert(src, 0)

While frontier is not empty:

current ← frontier.remove()

For each edge leaving current:

total ← cost.get(current) + edge.weight

If (not cost.contains(neighbor)):

cost.insert(neighbor, total)

frontier.insert(total, neighbor)

Else If cost.get(neighbor) > total:

cost.update(neighbor, total)

frontier.insert(total, neighbor)

End If

End For

End While

Return cost

End function

by the time a vertex is dequeued, we have found its best path

update