

# CS 31: Intro to Systems

## Misc. Threading

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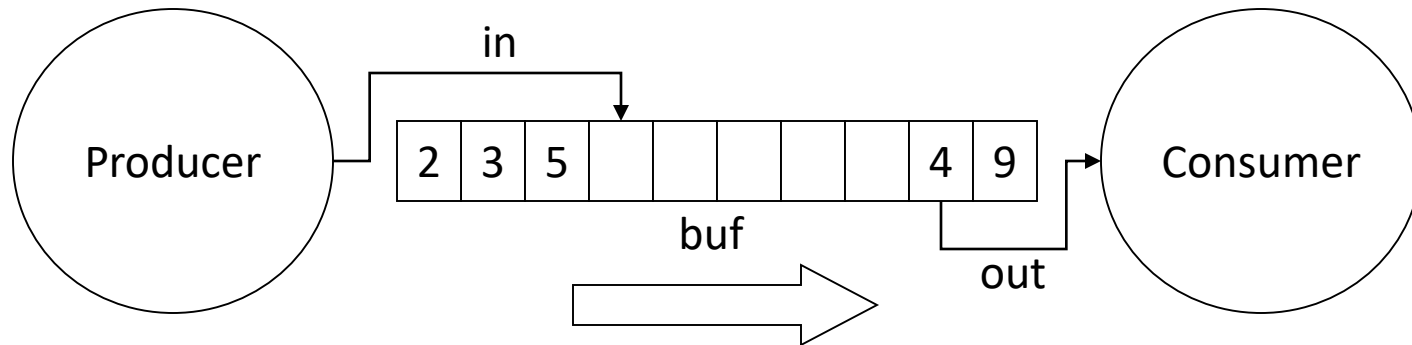
# Agenda

- Classic thread patterns
- Pthreads primitives and examples of other forms of synchronization:
  - Condition variables
  - Barriers
  - RW locks
  - Message passing
- Message passing: alternative to shared memory

# Common Thread Patterns

- Producer / Consumer (a.k.a. Bounded buffer)
- Thread pool (a.k.a. work queue)
- Thread per client connection

# The Producer/Consumer Problem



- Producer produces data, places it in shared buffer
- Consumer consumes data, removes from buffer
- Cooperation: Producer feeds Consumer
  - How does data get from Producer to Consumer?
  - How does Consumer wait for Producer?

# Producer/Consumer: Shared Memory

```
shared int buf[N], in = 0, out = 0;
```

## Producer

```
while (TRUE) {  
    buf[in] = Produce ();  
    in = (in + 1)%N;  
}
```

## Consumer

```
while (TRUE) {  
    Consume (buf[out]);  
    out = (out + 1)%N;  
}
```

- Data transferred in shared memory buffer.

# Producer/Consumer: Shared Memory

```
shared int buf[N], in = 0, out = 0;
```

## Producer

```
while (TRUE) {  
    buf[in] = Produce ();  
    in = (in + 1)%N;  
}
```

## Consumer

```
while (TRUE) {  
    Consume (buf[out]);  
    out = (out + 1)%N;  
}
```

- Data transferred in shared memory buffer.
- Is there a problem with this code?
  - A. Yes, this is broken.
  - B. No, this ought to be fine.

# This producer/consumer scenario requires synchronization to...

```
shared int buf[N], in = 0, out = 0;
```

## Producer

```
while (TRUE) {  
    buf[in] = Produce ();  
    in = (in + 1)%N;  
}
```

## Consumer

```
while (TRUE) {  
    Consume (buf[out]);  
    out = (out + 1)%N;  
}
```

- A. Avoid deadlock
- B. Avoid double writes or empty consumes of buf[] slots
- C. Protect a critical section with mutual exclusion
- D. Copy data from producer to consumer

# Adding Semaphores

```
shared int buf[N], in = 0, out = 0;  
shared sem filledslots = 0, emptyslots = N;
```

## Producer

```
while (TRUE) {  
    wait (X);  
    buf[in] = Produce ();  
    in = (in + 1)%N;  
    signal (Y);  
}
```

## Consumer

```
while (TRUE) {  
    wait (Z);  
    Consume (buf[out]);  
    out = (out + 1)%N;  
    signal (W);  
}
```

- Recall semaphores:
  - wait(): decrement sem and block if sem value < 0
  - signal(): increment sem and unblock a waiting process (if any)



# Suppose we now have two semaphores to protect our array. Where do we use them?

```
shared int buf[N], in = 0, out = 0;  
shared sem filledslots = 0, emptyslots = N;
```

## Producer

```
while (TRUE) {  
    wait (X);  
    buf[in] = Produce ();  
    in = (in + 1)%N;  
    signal (Y);  
}
```

## Consumer

```
while (TRUE) {  
    wait (Z);  
    Consume (buf[out]);  
    out = (out + 1)%N;  
    signal (W);  
}
```

Answer choice	X	Y	Z	W
A.	emptyslots	emptyslots	filledslots	filledslots
B.	emptyslots	filledslots	filledslots	emptyslots
C.	filledslots	emptyslots	emptyslots	filledslots

# Add Semaphores for Synchronization

```
shared int buf[N], in = 0, out = 0;  
shared sem filledslots = 0, emptyslots = N;
```

## Producer

```
while (TRUE) {  
    wait (emptyslots);  
    buf[in] = Produce ();  
    in = (in + 1)%N;  
    signal (filledslots);  
}
```

## Consumer

```
while (TRUE) {  
    wait (filledslots);  
    Consume (buf[out]);  
    out = (out + 1)%N;  
    signal (emptyslots);  
}
```

- Buffer empty, Consumer waits
- Buffer full, Producer waits
- Don't confuse synchronization with mutual exclusion

# Synchronization: More than Mutexes

- “I want to block a thread until something specific happens.”
  - Condition variable: wait for a condition to be true

# Condition Variables

- In the pthreads library:
  - pthread\_cond\_init: Initialize CV
  - pthread\_cond\_wait: Wait on CV
  - pthread\_cond\_signal: Wakeup one waiter
  - pthread\_cond\_broadcast: Wakeup all waiters
- Condition variable is associated with a mutex:
  1. Lock mutex, realize conditions aren't ready yet
  2. Temporarily give up mutex until CV signaled
  3. Reacquire mutex and wake up when ready

# Condition Variable Pattern

```
while (TRUE) {  
    //independent code  
  
    lock(m);  
    while (conditions bad)  
        wait(cond, m);  
  
    //proceed knowing that conditions are now good  
  
    signal (other_cond); // Let other thread know  
    unlock(m);  
}
```

# Condition Variable Example

```
shared int buf[N], in = 0, out = 0;
shared int count = 0; // # of items in buffer
shared mutex m;
shared cond notempty, notfull;
```

## Producer

```
while (TRUE) {
    item = Produce();

    lock(m);
    while (count == N)
        wait(m, notfull);

    buf[in] = item;
    in = (in + 1)%N;
    count += 1;

    signal (notempty);
    unlock(m);
}
```

## Consumer

```
while (TRUE) {
    lock(m);
    while (count == 0)
        wait(m, notempty);

    item = buf[out];
    out = (out + 1)%N;
    count -= 1;

    signal (notfull);
    unlock(m);

    Consume(item);
}
```

# Synchronization: More than Mutexes

- “I want to block a thread until something specific happens.”
  - Condition variable: wait for a condition to be true
- “I want all my threads to sync up at the same point.”
  - Barrier: wait for everyone to catch up.

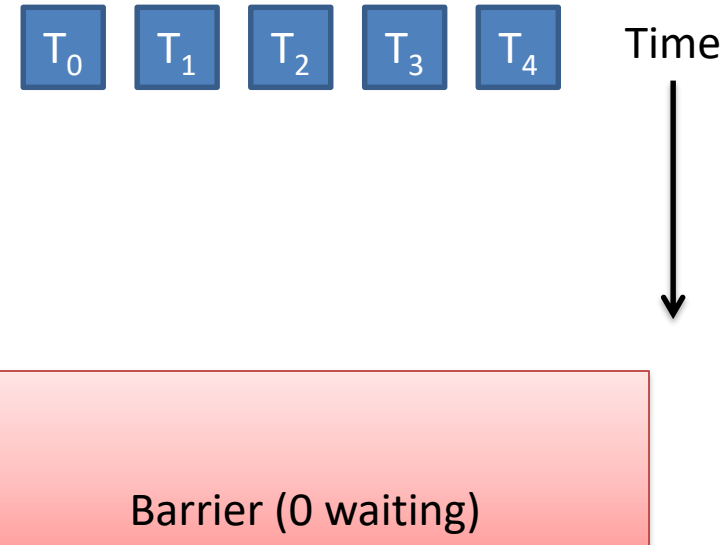
# Barriers

- Used to coordinate threads, but also other forms of concurrent execution.
- Often found in simulations that have discrete rounds. (e.g., game of life)



# Barrier Example, N Threads

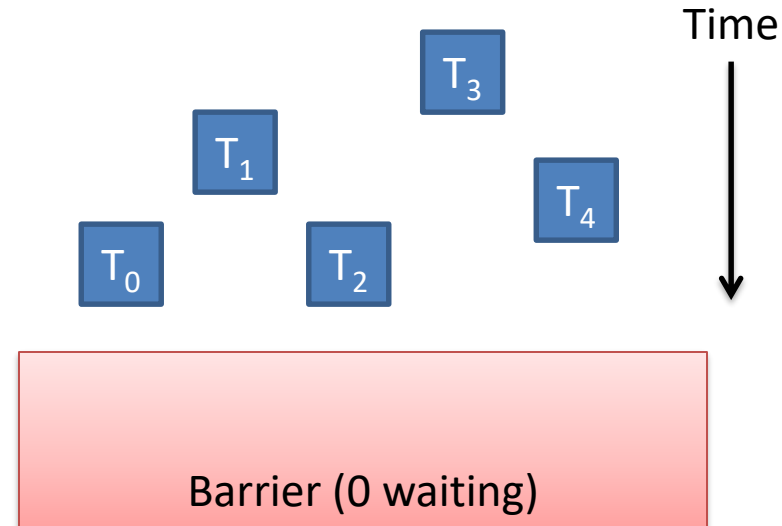
```
shared barrier b;  
  
init_barrier(&b, N);  
  
create_threads(N, func);  
  
void *func(void *arg) {  
    while (...) {  
        compute_sim_round()  
        barrier_wait(&b)  
    }  
}
```



# Barrier Example, N Threads

```
shared barrier b;  
  
init_barrier(&b, N);  
  
create_threads(N, func);  
  
void *func(void *arg) {  
    while (...) {  
        compute_sim_round()  
        barrier_wait(&b)  
    }  
}
```

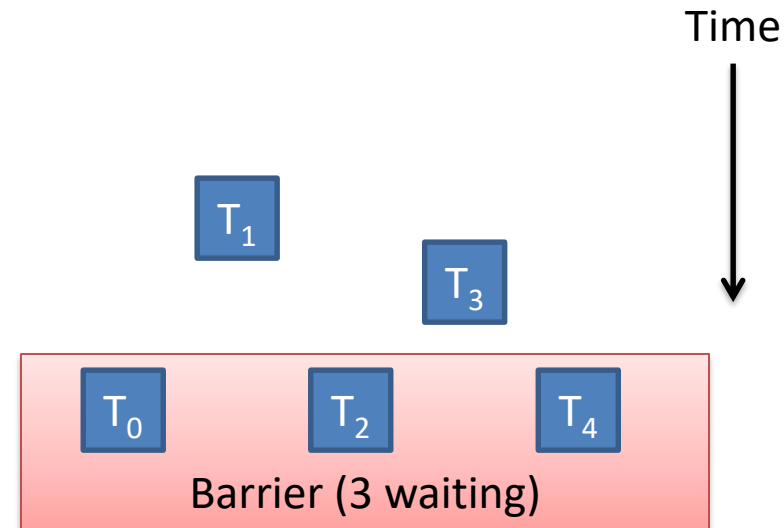
Threads make progress computing current round at different rates.



# Barrier Example, N Threads

```
shared barrier b;  
  
init_barrier(&b, N);  
  
create_threads(N, func);  
  
void *func(void *arg) {  
    while (...) {  
        compute_sim_round()  
        barrier_wait(&b)  
    }  
}
```

Threads that make it to barrier must wait for all others to get there.



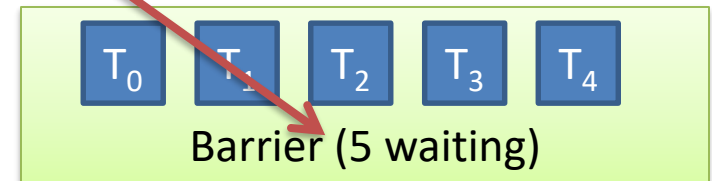
# Barrier Example, N Threads

```
shared barrier b;  
  
init_barrier(&b, N);  
create_threads(N, func);  
  
void *func(void *arg) {  
    while (...) {  
        compute_sim_round()  
        barrier_wait(&b)  
    }  
}
```

Barrier allows threads to pass when N threads reach it.

Time  
↓

Matches

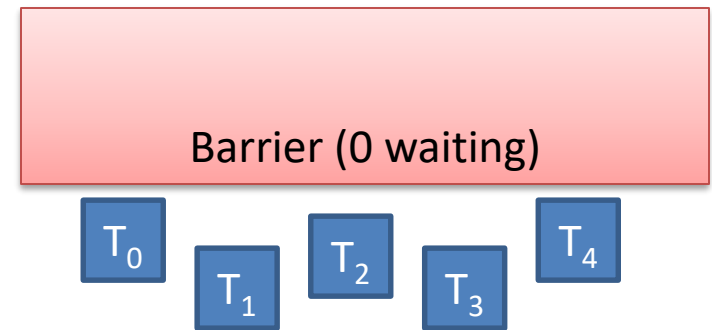


# Barrier Example, N Threads

```
shared barrier b;  
  
init_barrier(&b, N);  
  
create_threads(N, func);  
  
void *func(void *arg) {  
    while (...) {  
        compute_sim_round()  
        barrier_wait(&b)  
    }  
}
```

Threads compute next round, wait on barrier again, repeat...

Time  
↓



# Synchronization: More than Mutexes

- “I want to block a thread until something specific happens.”
  - Condition variable: wait for a condition to be true
- “I want all my threads to sync up at the same point.”
  - Barrier: wait for everyone to catch up.
- “I want my threads to share a critical section when they’re reading, but still safely write.”
  - Readers/writers lock: distinguish how lock is used

# Readers/Writers

- Readers/Writers Problem:
  - An object is shared among several threads
  - Some threads only read the object, others only write it
  - We can safely allow multiple readers
  - But only one writer
- `pthread_rwlock_t`:
  - `pthread_rwlock_init`: initialize rwlock
  - `pthread_rwlock_rdlock`: lock for reading
  - `pthread_rwlock_wrlock`: lock for writing

# Common Thread Patterns

- Producer / Consumer (a.k.a. Bounded buffer)
- Thread pool (a.k.a. work queue)
- Thread per client connection



# Thread Pool / Work Queue

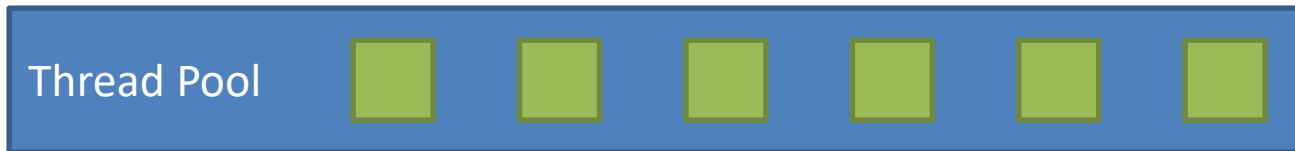
- Common way of structuring threaded apps:



# Thread Pool / Work Queue

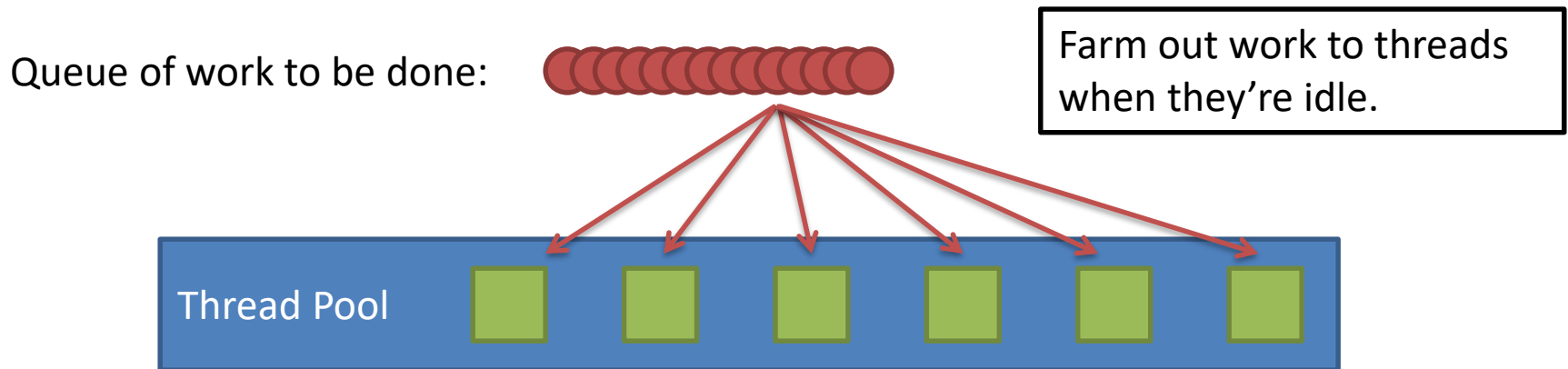
- Common way of structuring threaded apps:

Queue of work to be done: 




# Thread Pool / Work Queue

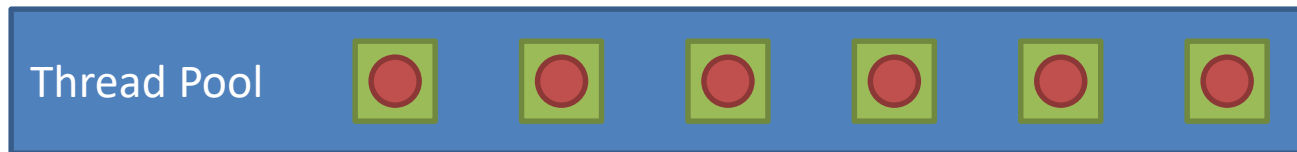
- Common way of structuring threaded apps:



# Thread Pool / Work Queue

- Common way of structuring threaded apps:

Queue of work to be done: 



As threads finish work at their own rate, they grab the next item in queue.

Common for “embarrassingly parallel” algorithms.

Works across the network too!

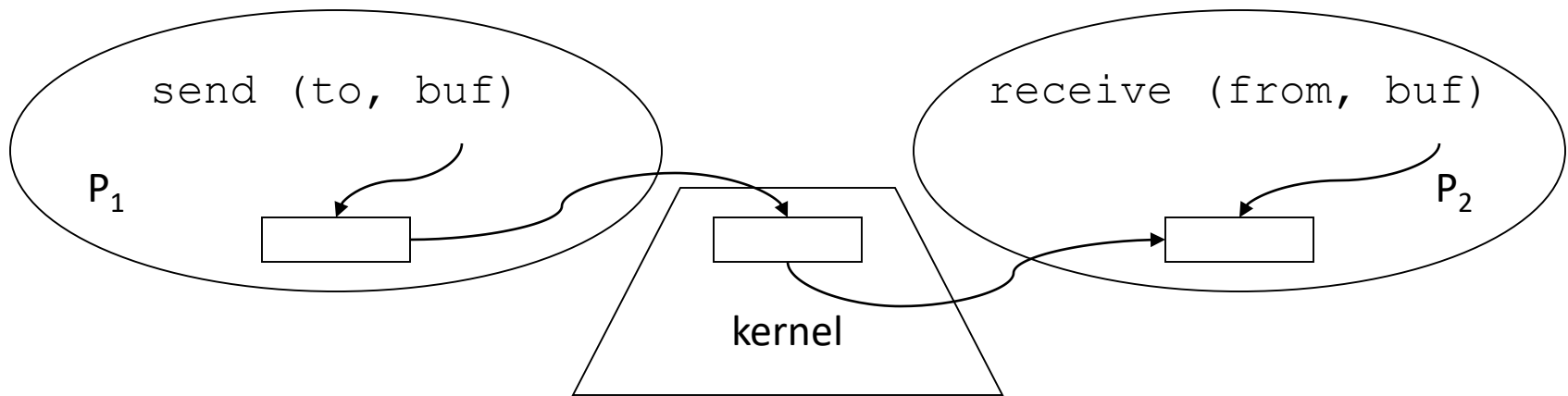
# Thread Per Client

- Consider Web server:
  - Client connects
  - Client asks for a page:
    - `http://web.cs.swarthmore.edu/~kwebb/cs31`
    - “Give me `/~kwebb/cs31`”
  - Server looks through file system to find path (I/O)
  - Server sends back html for client browser (I/O)
- Web server does this for MANY clients at once

# Thread Per Client

- Server “main” thread:
  - Wait for new connections
  - Upon receiving one, spawn new client thread
  - Continue waiting for new connections, repeat...
- Client threads:
  - Read client request, find files in file system
  - Send files back to client
  - Nice property: Each client is independent
  - Nice property: When a thread does I/O, it gets blocked for a while. OS can schedule another one.

# Message Passing



- Operating system mechanism for IPC
  - `send (destination, message_buffer)`
  - `receive (source, message_buffer)`
- Data transfer: in to and out of kernel message buffers
- Synchronization: can't receive until message is sent

# Suppose we're using message passing, will this code operate correctly?

```
/* NO SHARED MEMORY */
```

## Producer

```
int item;
```

```
while (TRUE) {  
    item = Produce ();  
    send (Consumer, &item);  
}
```

## Consumer

```
int item;
```

```
while (TRUE) {  
    receive (Producer, &item);  
    Consume (item);  
}
```

- A. No, there is a race condition.
- B. No, we need to protect *item*.
- C. Yes, this code is correct.



This code is correct and relatively simple. Why don't we always just use message passing (vs semaphores, etc.)?

```
/* NO SHARED MEMORY */
```

Producer

```
int item;
```

```
while (TRUE) {  
    item = Produce ();  
    send (Consumer, &item);  
}
```

Consumer

```
int item;
```

```
while (TRUE) {  
    receive (Producer, &item);  
    Consume (item);  
}
```

- A. Message passing copies more data.
- B. Message passing only works across a network.
- C. Message passing is a security risk.
- D. We usually do use message passing!

# Issues with Message Passing

- Who should messages be addressed to?
  - ports (mailboxes) rather than processes/threads
- What if it wants to receive from anyone?
  - `pid = receive (*, msg)`
- Synchronous (blocking) vs. asynchronous (non-blocking)
- Kernel buffering: how many sends w/o receives?
- Good paradigm for IPC over networks

# Summary

- Many ways to solve the same classic problems
  - Producer/Consumer: semaphores, CVs, messages
- There's more to synchronization than just mutual exclusion!
  - CVs, barriers, RWlocks, and others.
- Message passing doesn't require shared mem.
  - Useful for “threads” on different machines.