CS 31: Intro to Systems Digital Logic

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Today

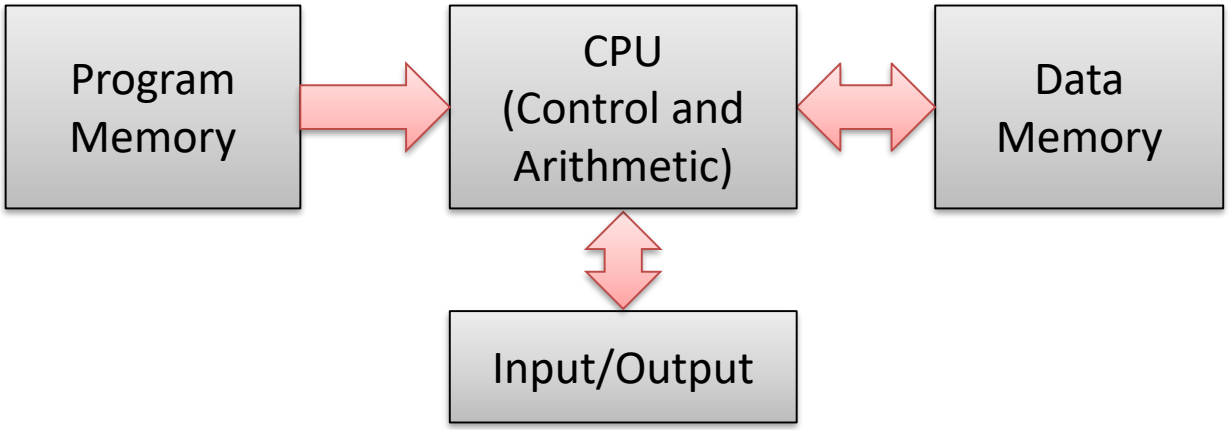
- Hardware basics
  - Machine memory models
  - Digital signals
  - Logic gates

Circuits: Borrow some paper if you need to!

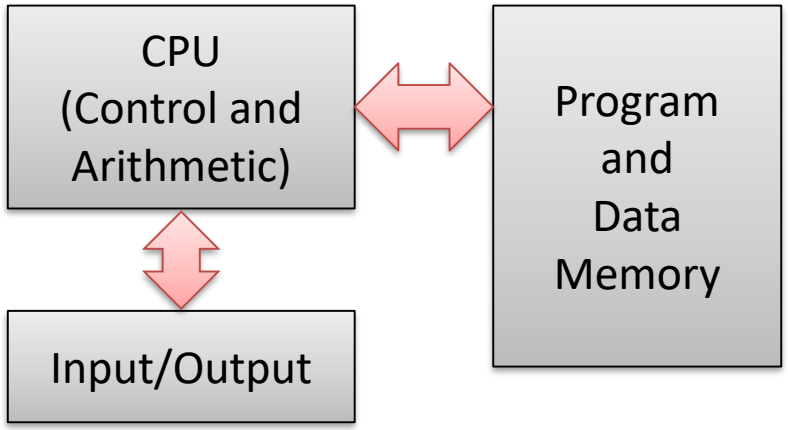
- Manipulating/Representing values in hardware
  - Adders
  - Storage & memory (latches)

Hardware Models (1940's)

- Harvard Architecture:



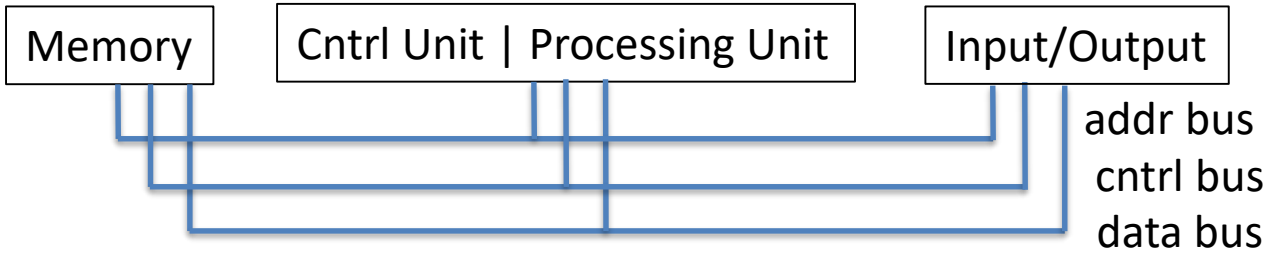
- Von Neumann Architecture:

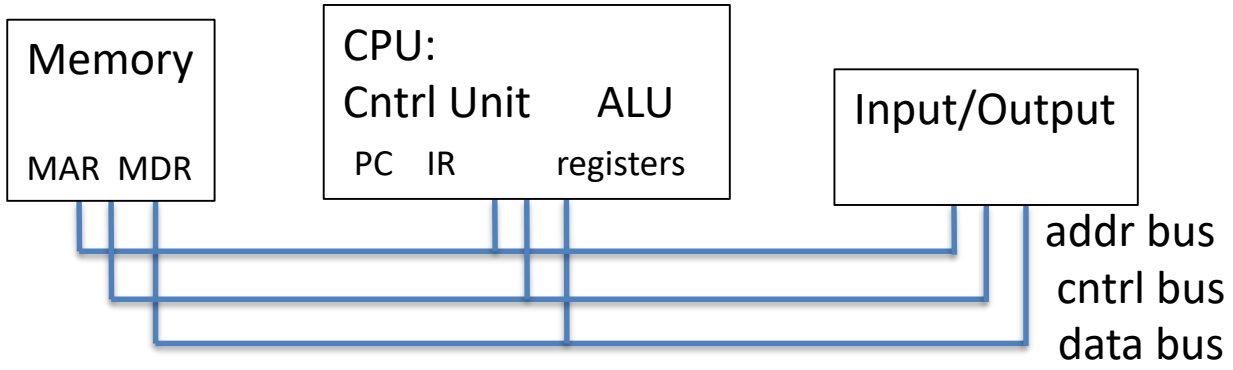


Von Neumann Architecture Model

- Computer is a generic computing machine:
  - Based on Alan Turing's Universal Turing Machine
  - Stored program model: computer stores program rather than encoding it (feed in data and instructions)
  - No distinction between data and instructions memory

- 5 parts connected by buses (wires):
  - Memory, Control, Processing, Input, Output





Memory: data and instructions are stored in memory
memory is addressable: addr 0, 1, 2, …

- Memory Address Register: address to read/write
- Memory Data Register: value to read/write

Processing Unit: executes instrs selected by cntrl unit

- ALU (artithmetic logic unit): simmple functional units: ADD, SUB…
- Registers: temporary storage directly accessible by instructions

Control unit: determines order in which instrs execute

- PC: program counter: address of next instruction
- IR: holds current instruction
- clock based instr by instr control: clock signal+IR trigger state changes

Input/Output: keyboard (can trigger actions), terminal, disk, …

"Register"
Small, very vast storage space
Fixed size (e.g., 32 bits)
Stores what is currently being worked on

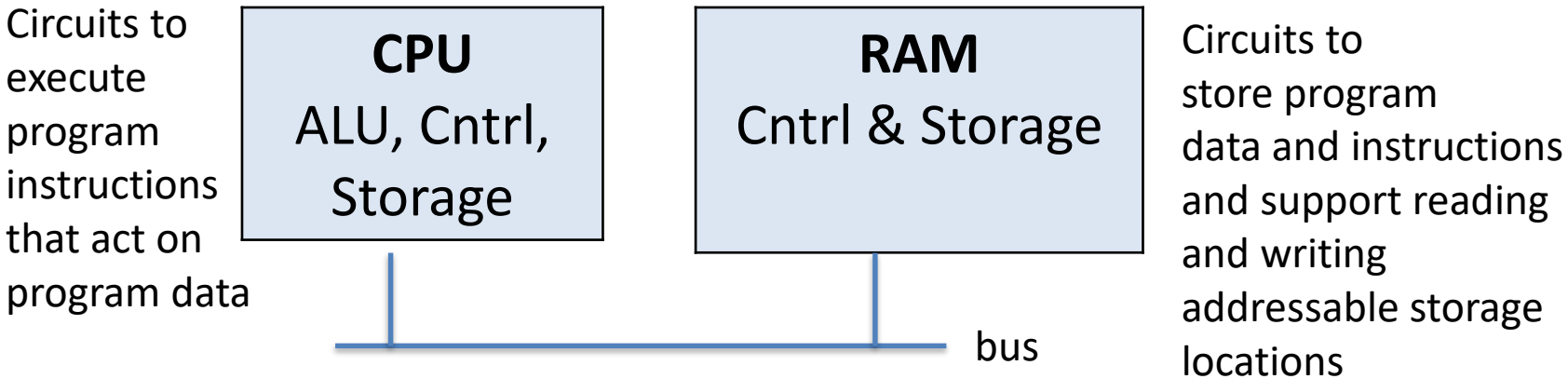
Digital Computers

- All input is discrete (driven by periodic clock)

- All signals are binary (0: no voltage, 1: voltage)

  data, instructions, control signals, arithmetic, clock

- To run program, need different types of circuits



Goal: Build a CPU (model)

Three main classifications of HW circuits:

1. ALU: implement arithmetic & logic functionality

   (ex) adder to add two values together

2. Storage: to store binary values

   (ex) Register File: set of CPU registers, Also: main memory (RAM)

3. Control: support/coordinate instruction execution

   (ex) fetch the next instruction to execute

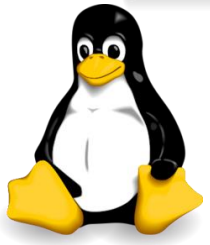
Abstraction

User / Programmer
Wants low complexity

Applications
Specific functionality

Software library
Reusable functionality

Operating system
Manage resources



Complex devices
Compute & I/O

Abstraction

Hardware Circuits

Logic Gates

Transistors

Here be dragons.
(Electrical Engineering)
…
(Physics)

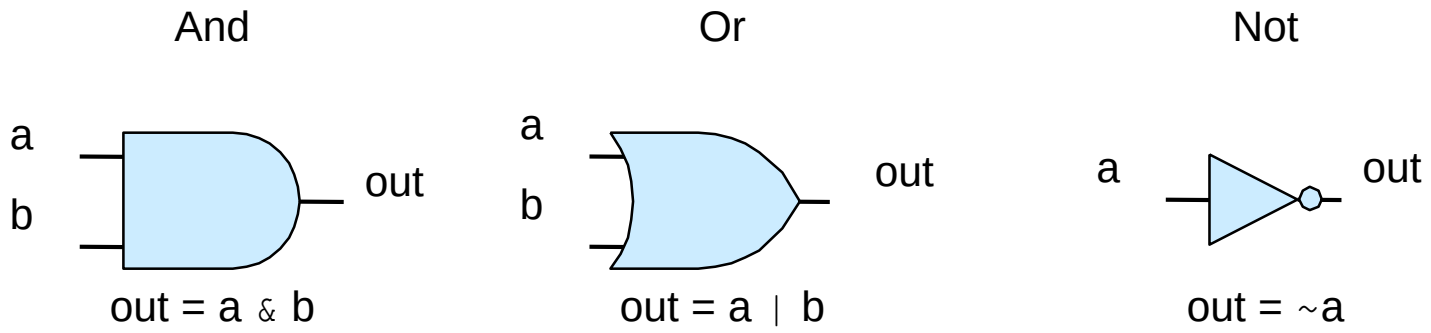
Complex devices
Compute & I/O

Logic Gates

Input: Boolean value(s) (high and low voltages for 1 and 0)

Output: Boolean value result of boolean function

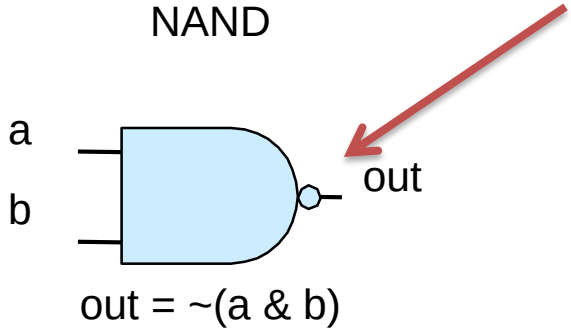
Always present, but may change when input changes

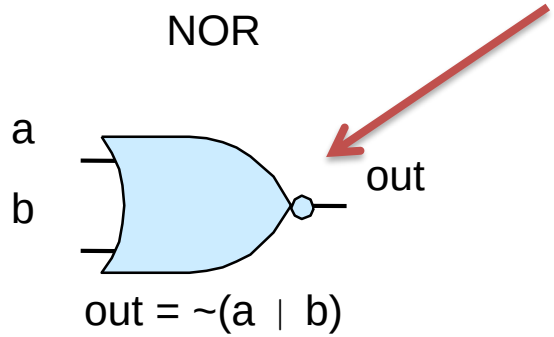


A	B	A & B	A | B	~A
0	0	0	0	1
0	1	0	1	1
1	0	0	1	0
1	1	1	1	0

More Logic Gates

Note the circle on the output.
This means “negate it.”

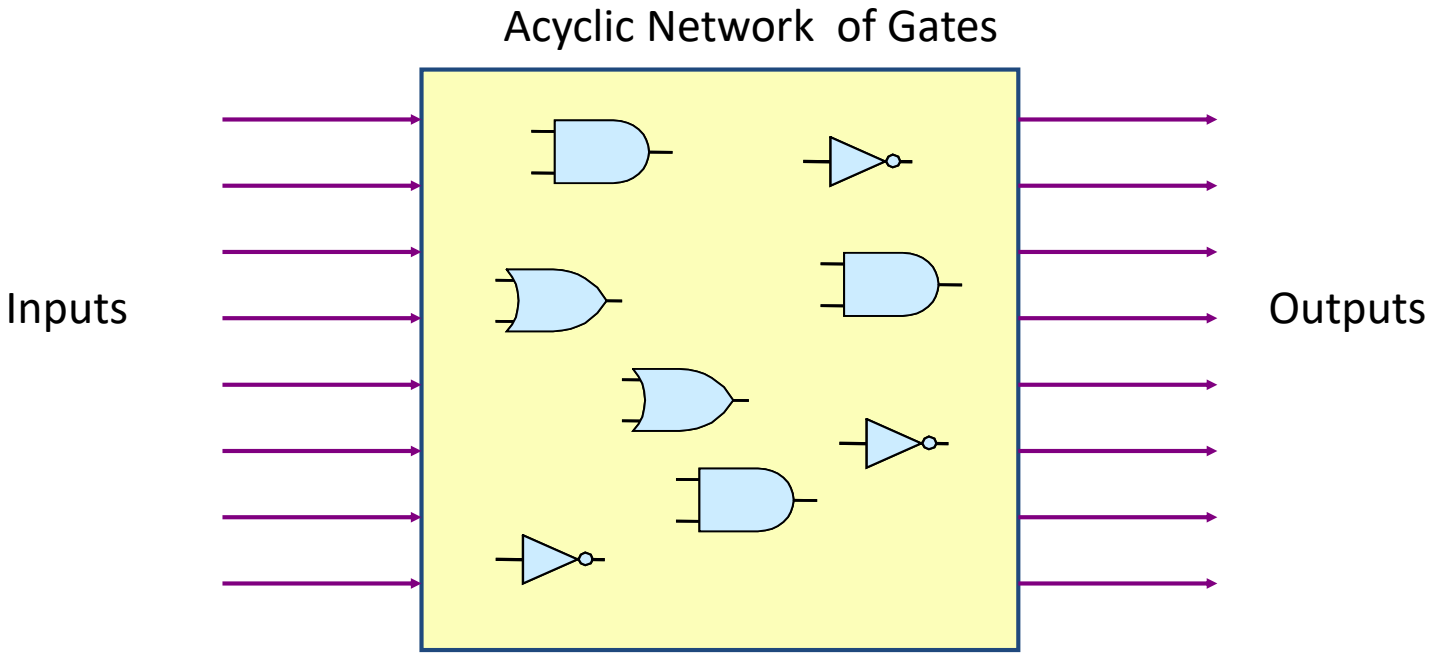




A	B	A NAND B	A NOR B
0	0	1	1
0	1	1	0
1	0	1	0
1	1	0	0

Combinational Logic Circuits

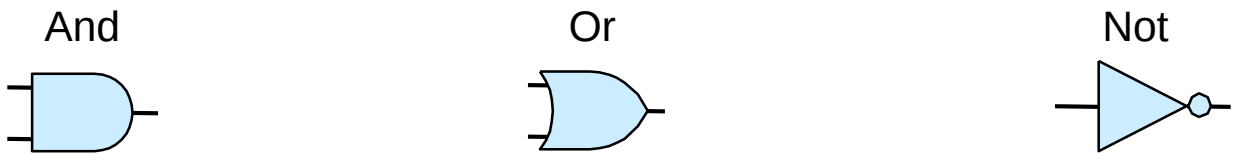
- Build up higher level processor functionality from basic gates

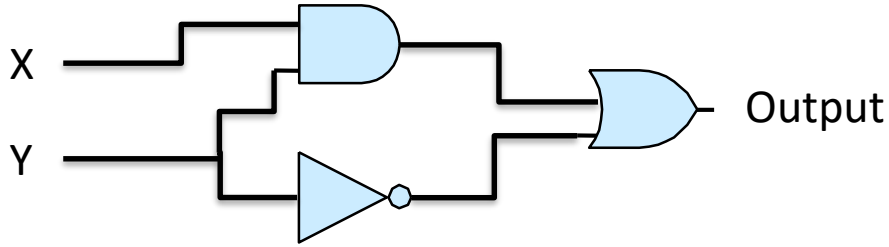


Outputs are boolean functions of inputs

Outputs continuously respond to changes to inputs

What does this circuit output?





Clicker Choices

X	Y	Out_A	Out_B	Out_C	Out_D	Out_E
0	0	0	1	0	1	0
0	1	0	1	0	0	1
1	0	1	0	1	1	1
1	1	0	0	1	1	0

What can we do with these?

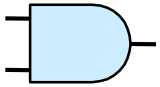
- Build-up XOR from basic gates (AND, OR, NOT)

A	B	A ^ B
0	0	0
0	1	1
1	0	1
1	1	0

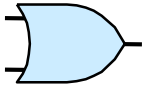
Q: When is A^B ==1?

Which of these is an XOR circuit?

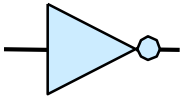
And



Or



Not

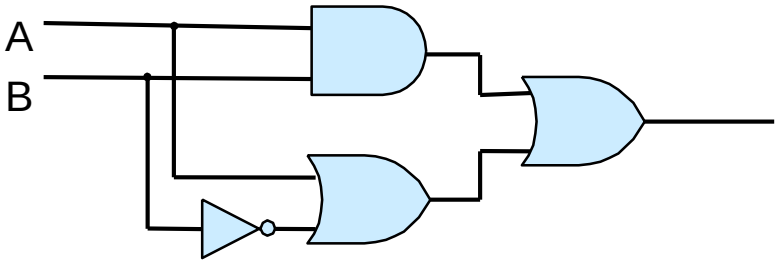


Draw an XOR circuit using AND, OR, and NOT gates.

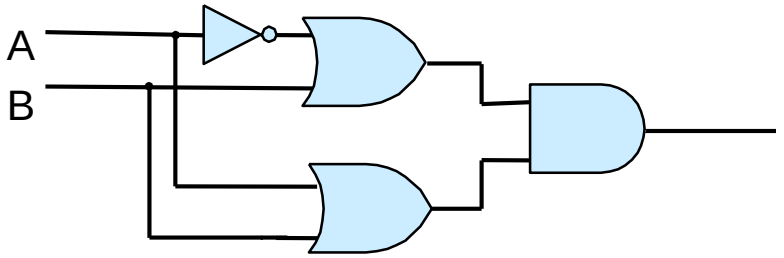
I'll show you the clicker options after you've had some time.

Which of these is an XOR circuit?

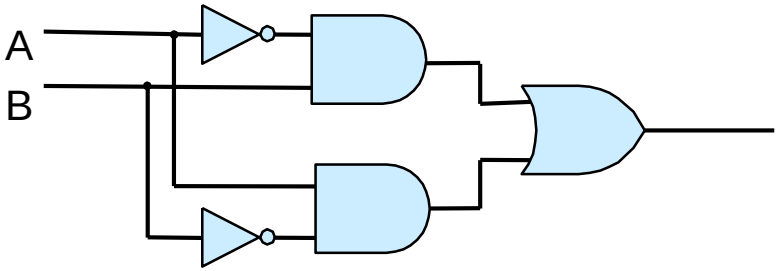
A:



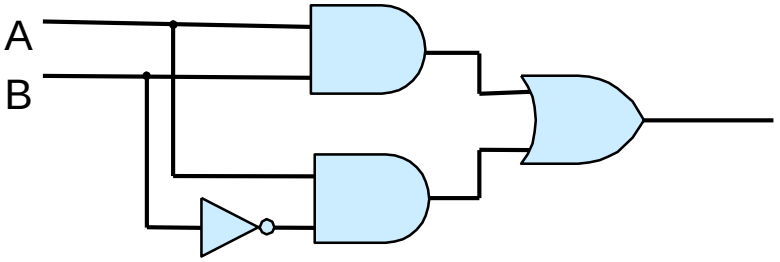
B:



C:



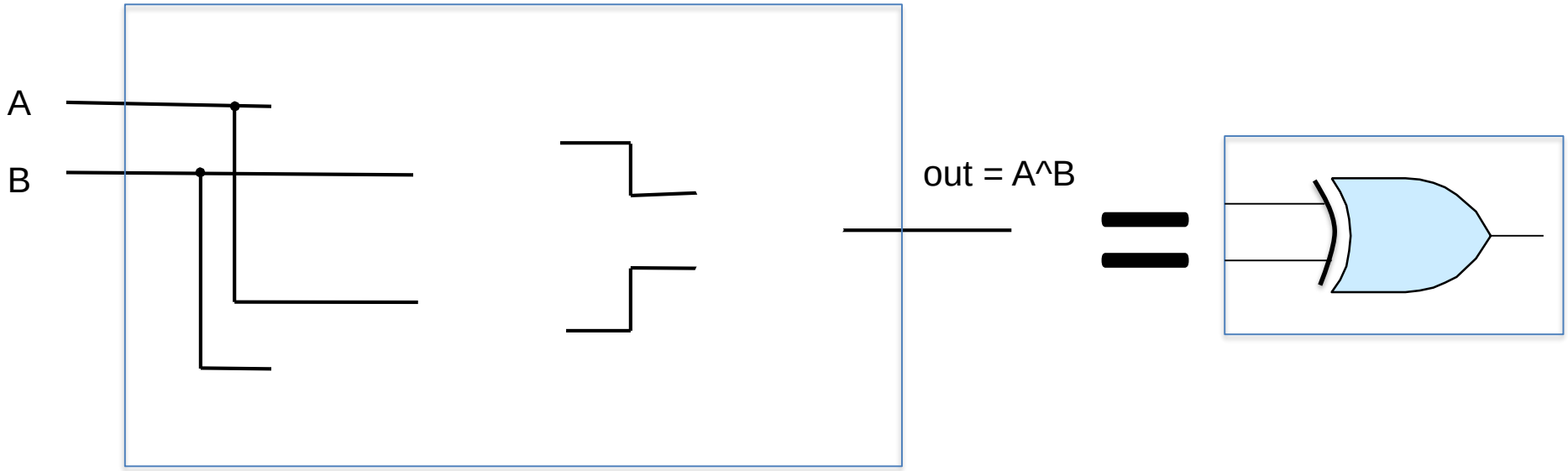
D:



E: None of these are XOR.

XOR Circuit: Abstraction

```
A^B  ==  (~A & B) | (A & ~B)
```




```
A:0 B:0 A^B:
A:0 B:1 A^B:
```

```
A:1 B:0 A^B:
A:1 B:1 A^B:
```

Digital Circuits - Building a CPU

Three main classifications of HW circuits:

1. ALU: implement arithmetic & logic functionality

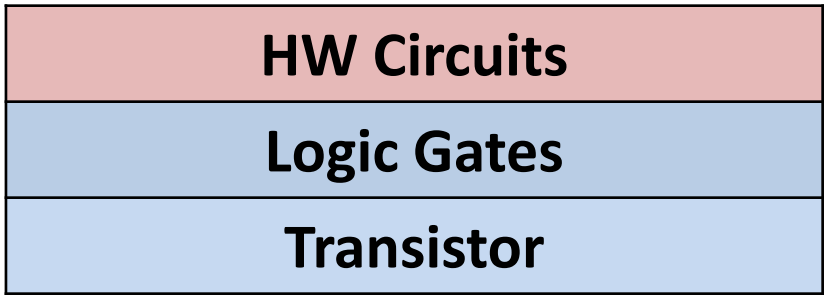
   (ex) adder to add two values together

2. Storage: to store binary values

   (ex) Register File: set of CPU registers

3. Control: support/coordinate instruction execution

   (ex) fetch the next instruction to execute



Digital Circuits - Building a CPU

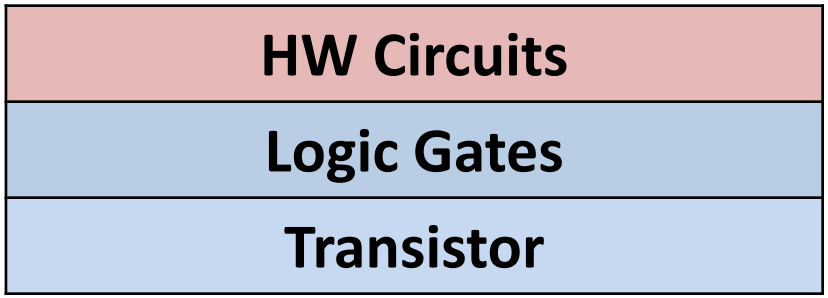
Three main classifications of HW circuits:

1. ALU: implement arithmetic & logic functionality

   (ex) adder to add two values together

Start with ALU components (e.g., adder)

Combine into ALU!



Arithmetic Circuits

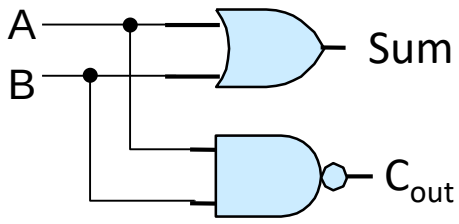
- 1 bit adder: A+B
- Two outputs:
  1. Obvious one: the sum
  2. Other one: ??

A	B	Sum(A+B)	Cout
0	0		
0	1		
1	0		
1	1		

Which of these circuits is a one-bit adder?

A	B	Sum (A+B)	Cout
0	0	0	0
0	1	1	0
1	0	1	0
1	1	0	1

A:



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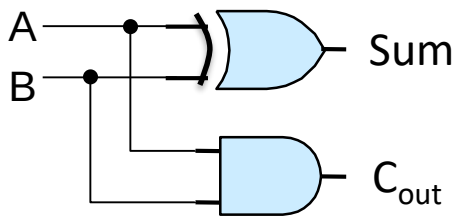

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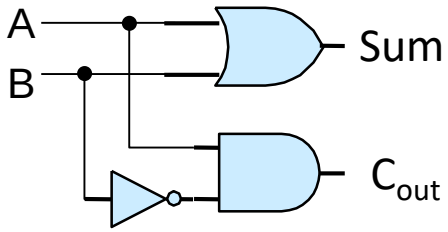

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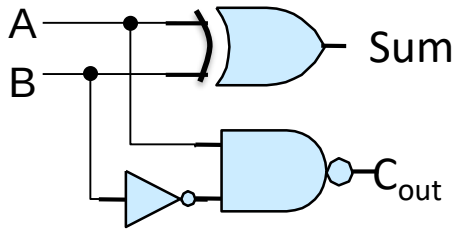


More than one bit?

- When adding, sometimes have *carry in* too

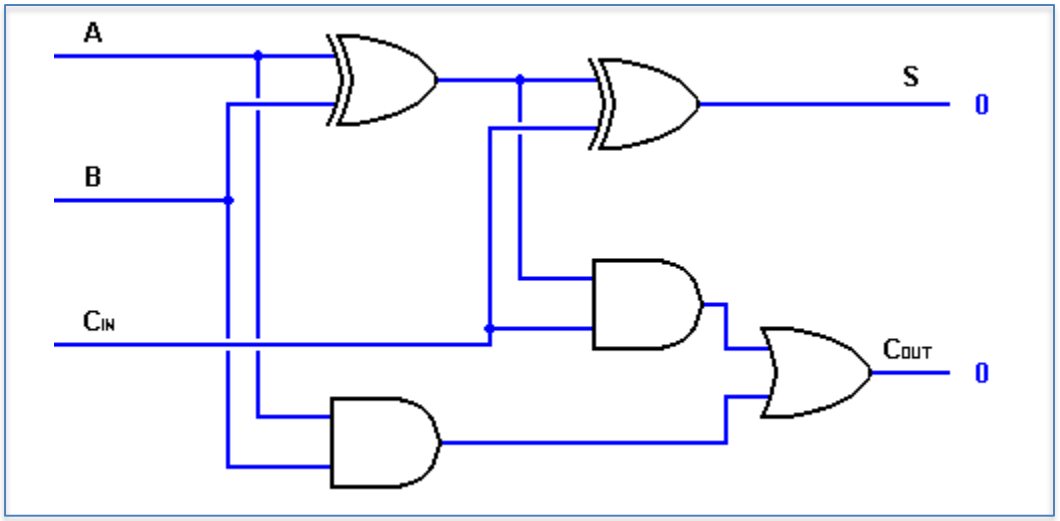
```
   0011010
+  0001111
```

One-bit (full) adder

Need to include:

Carry-in & Carry-out

A	B	Cin	Sum	Cout
0	0	0	0	0
0	1	0	1	0
1	0	0	1	0
1	1	0	0	1
0	0	1	1	0
0	1	1	0	1
1	0	1	0	1
1	1	1	1	1



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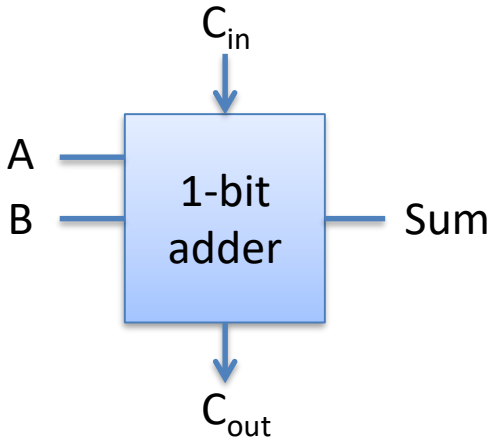
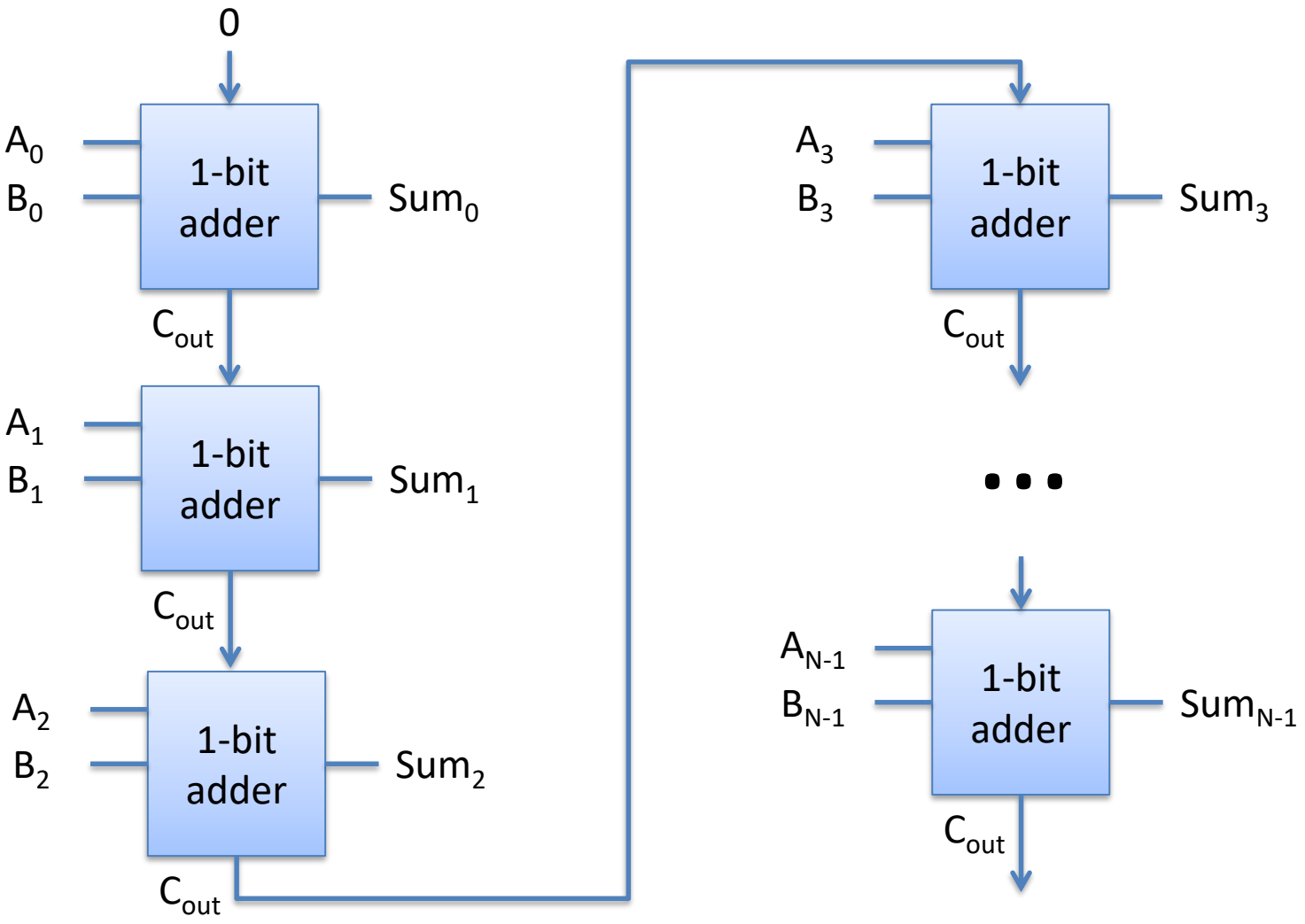
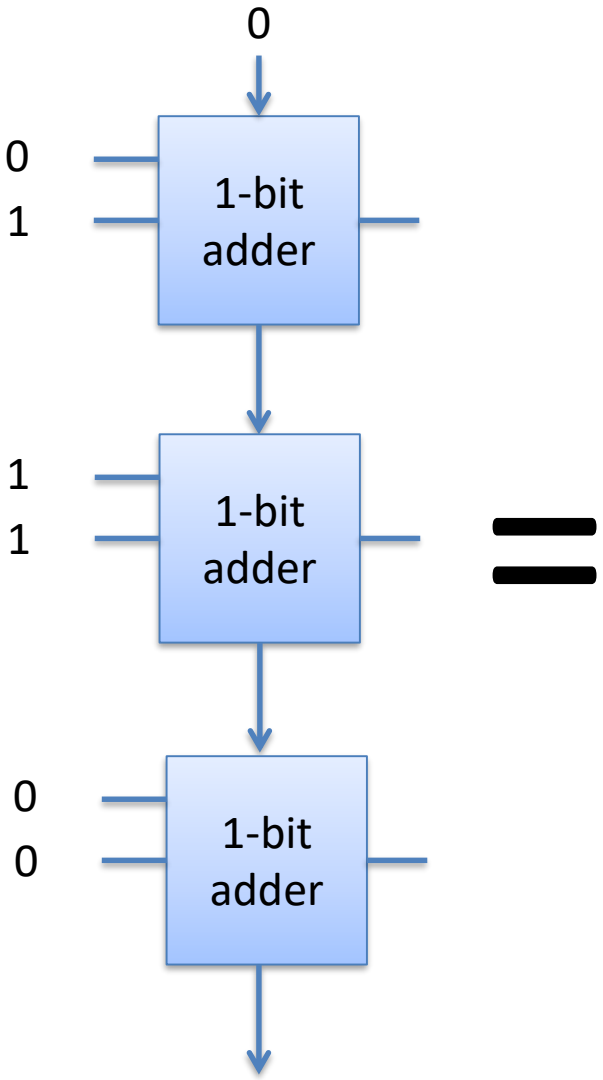


Multi-bit Adder (Ripple-carry Adder)



Three-bit Adder (Ripple-carry Adder)

010 (2)
+ 011 (3)



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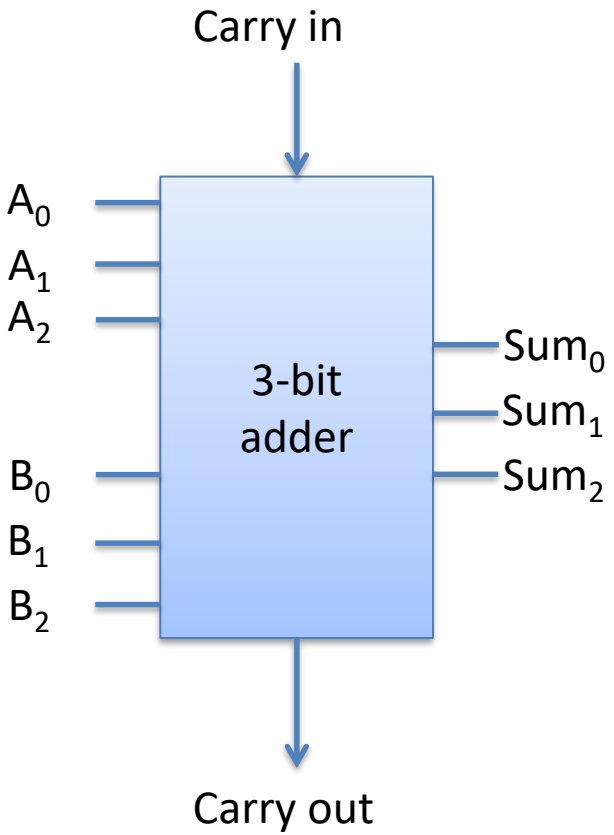


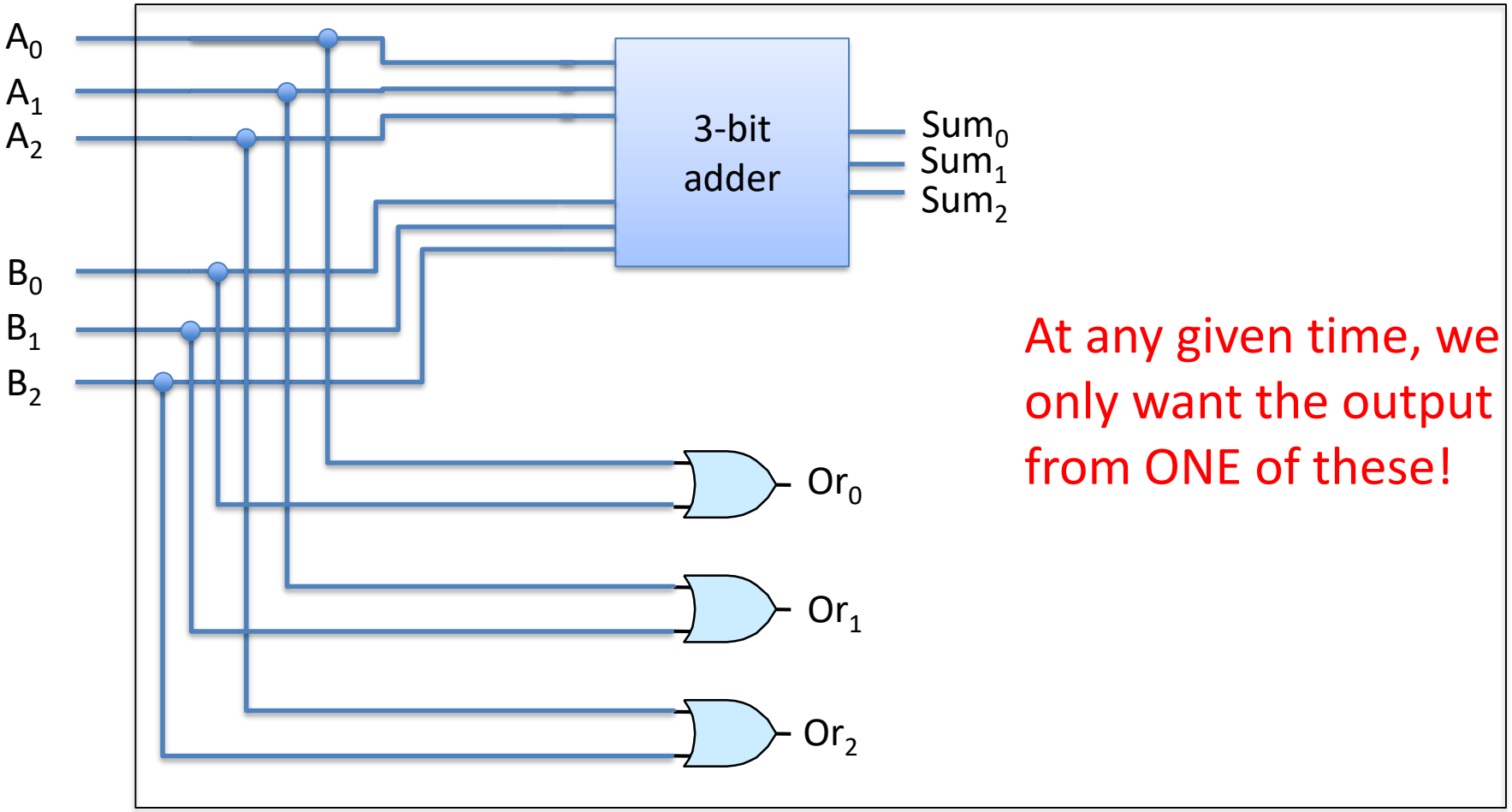
Arithmetic Logic Unit (ALU)

- One component that knows how to manipulate bits in multiple ways
  - Addition
  - Subtraction
  - Multiplication / Division
  - Bitwise AND, OR, NOT, etc.

- Built by combining components
  - Take advantage of sharing HW when possible (e.g., subtraction using adder)

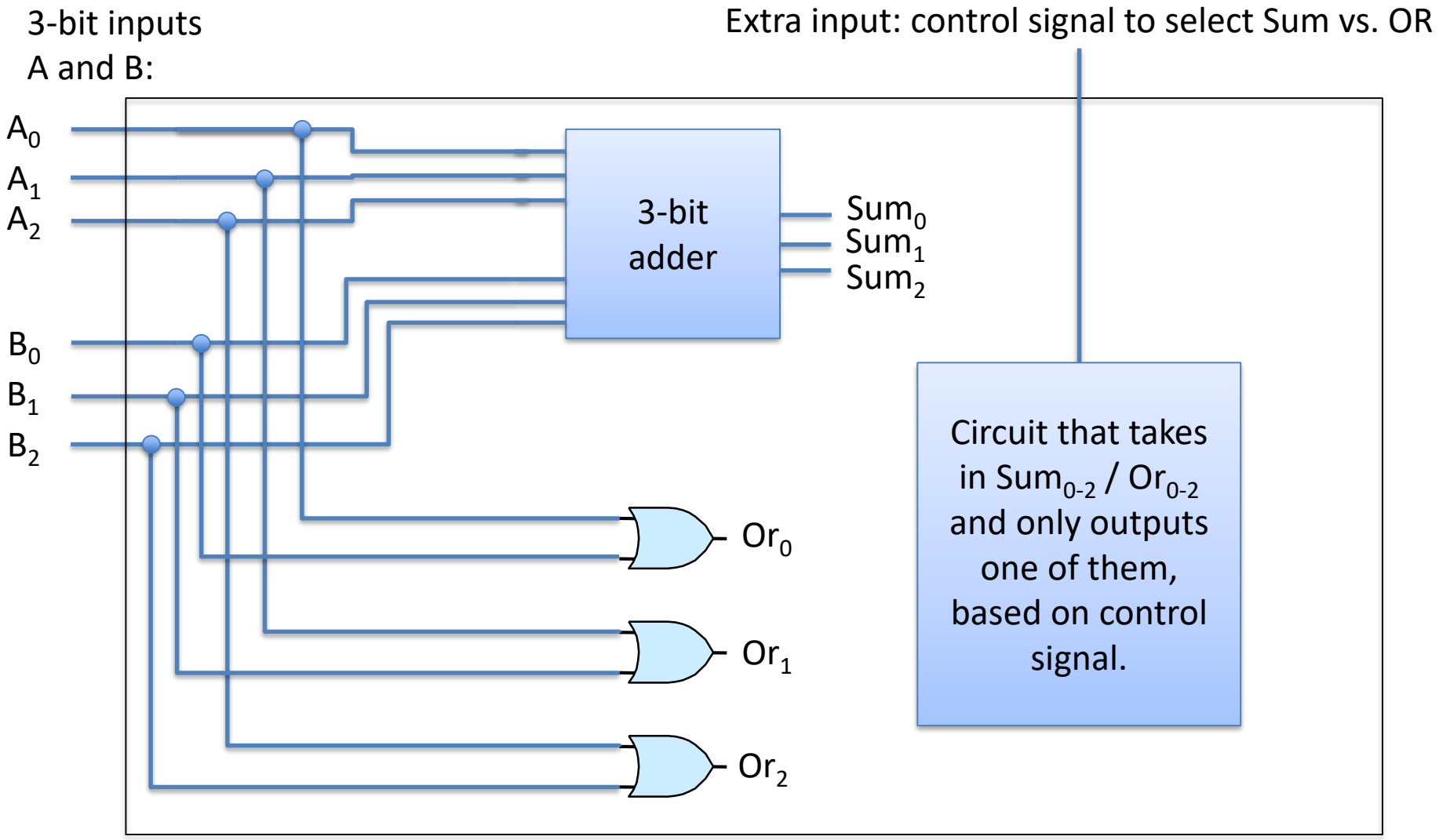
Simple 3-bit ALU: Add and bitwise OR

3-bit inputs
A and B:



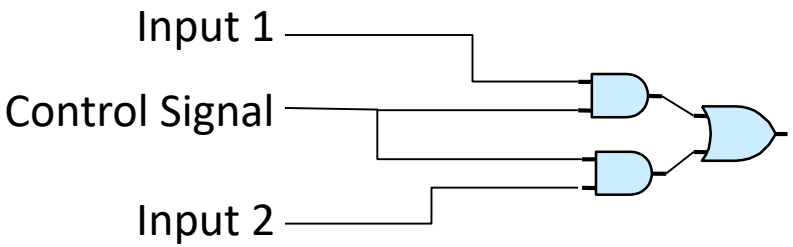
At any given time, we only want the output from ONE of these!

Simple 3-bit ALU: Add and bitwise OR



Which of these circuits lets us select between two inputs?

A:



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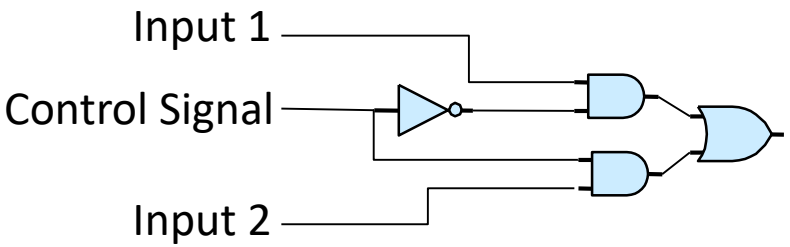

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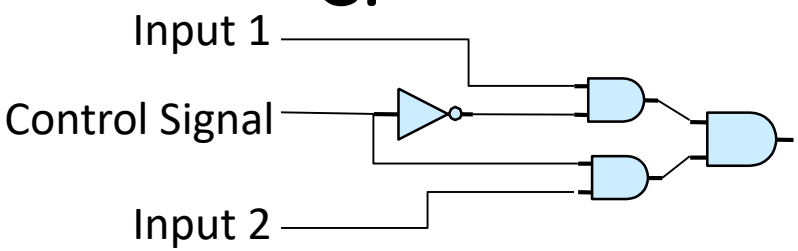
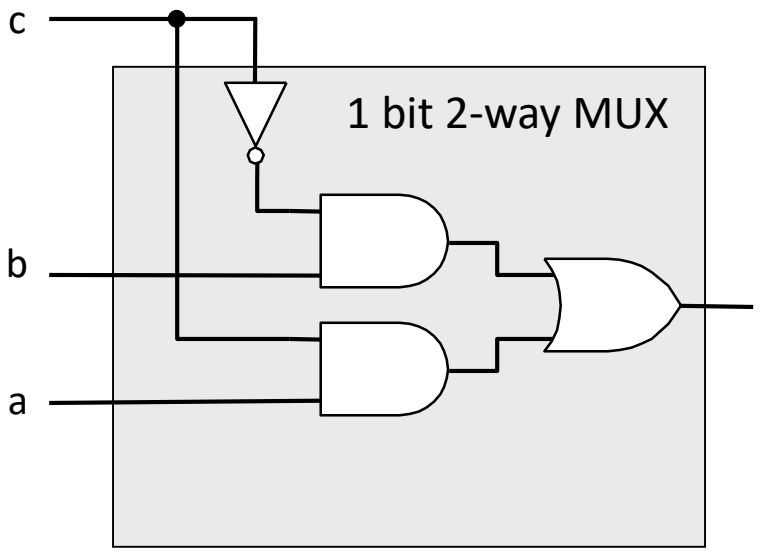


Multiplexor: Chooses an input value

Inputs: 2^N data inputs, N signal bits

Output: is one of the 2^N input values

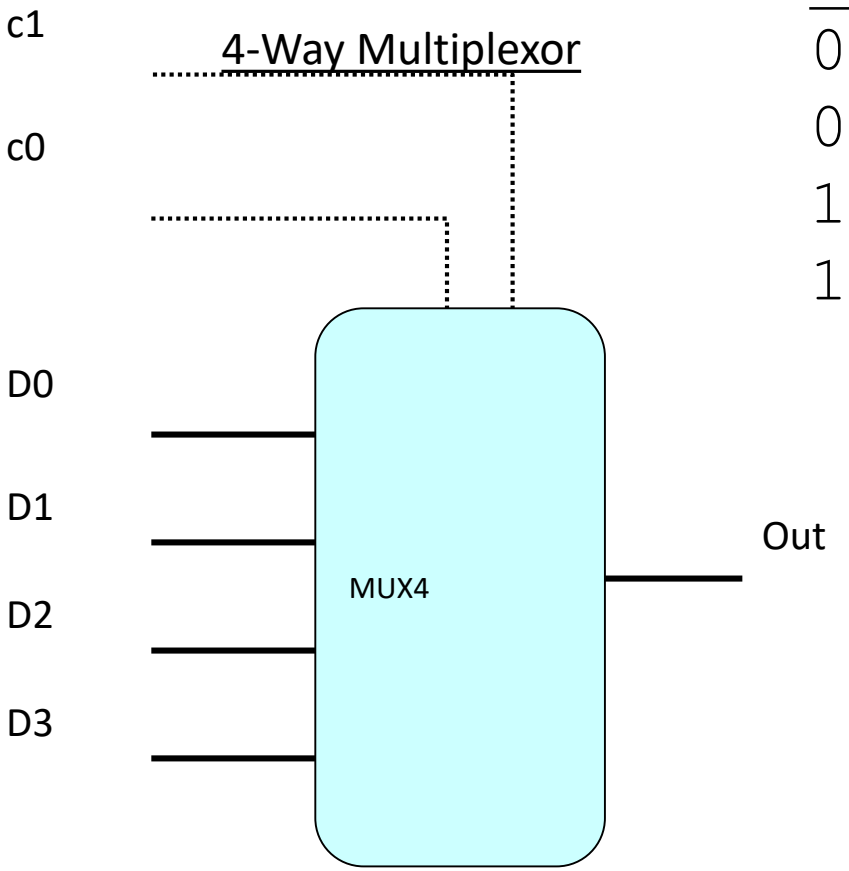



```
out = (c & a)|(~c &b)
```

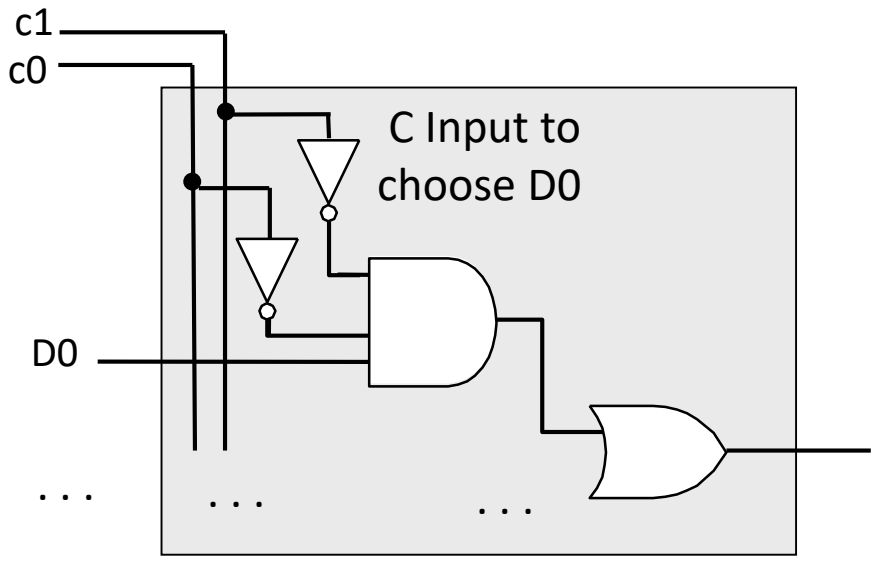
- Control signal c, chooses the input for output
  - When c is 1: choose a, when c is 0: choose b

N-Way Multiplexor

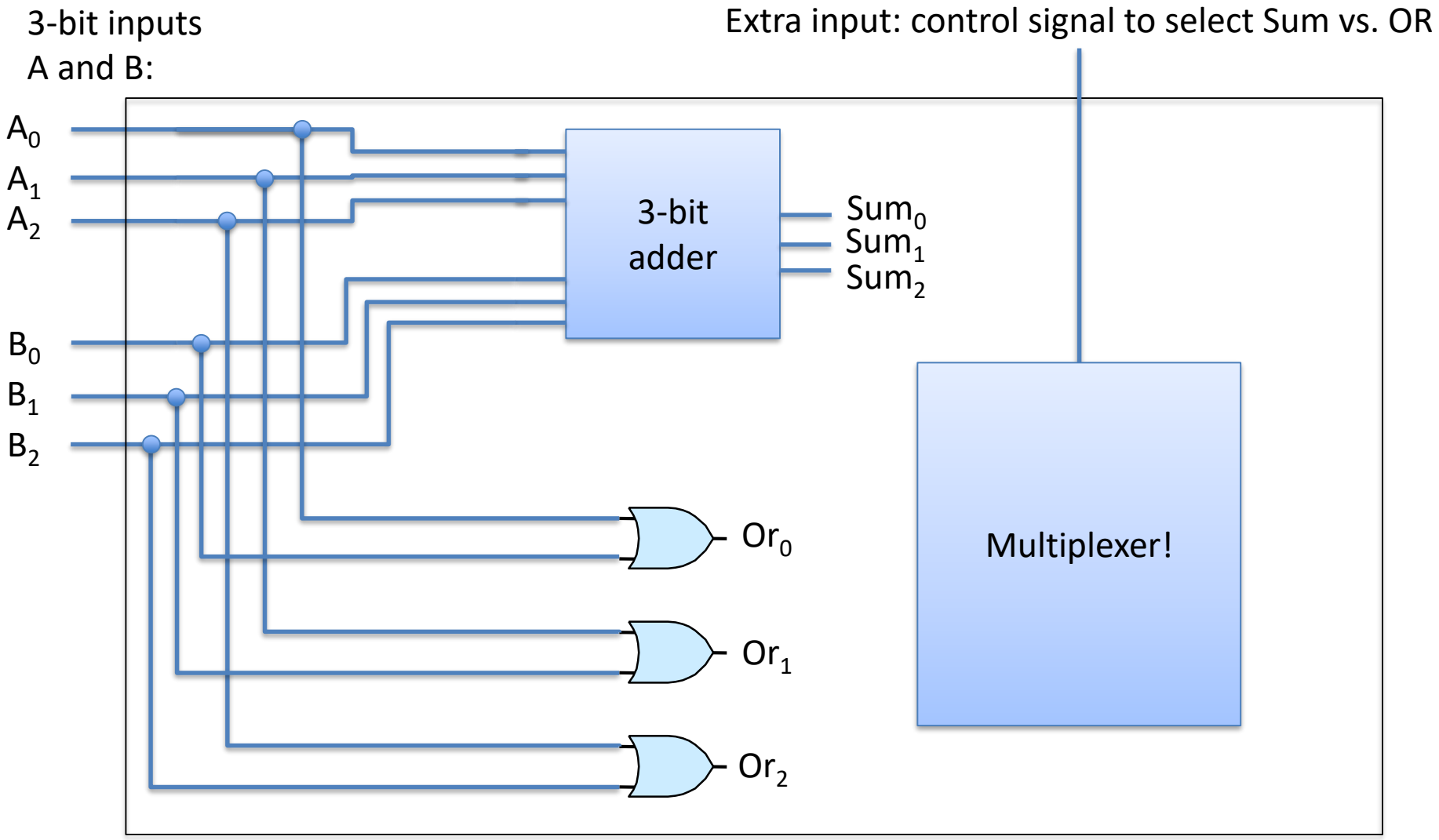
Choose one of N inputs, need $\log_2 N$ select bits



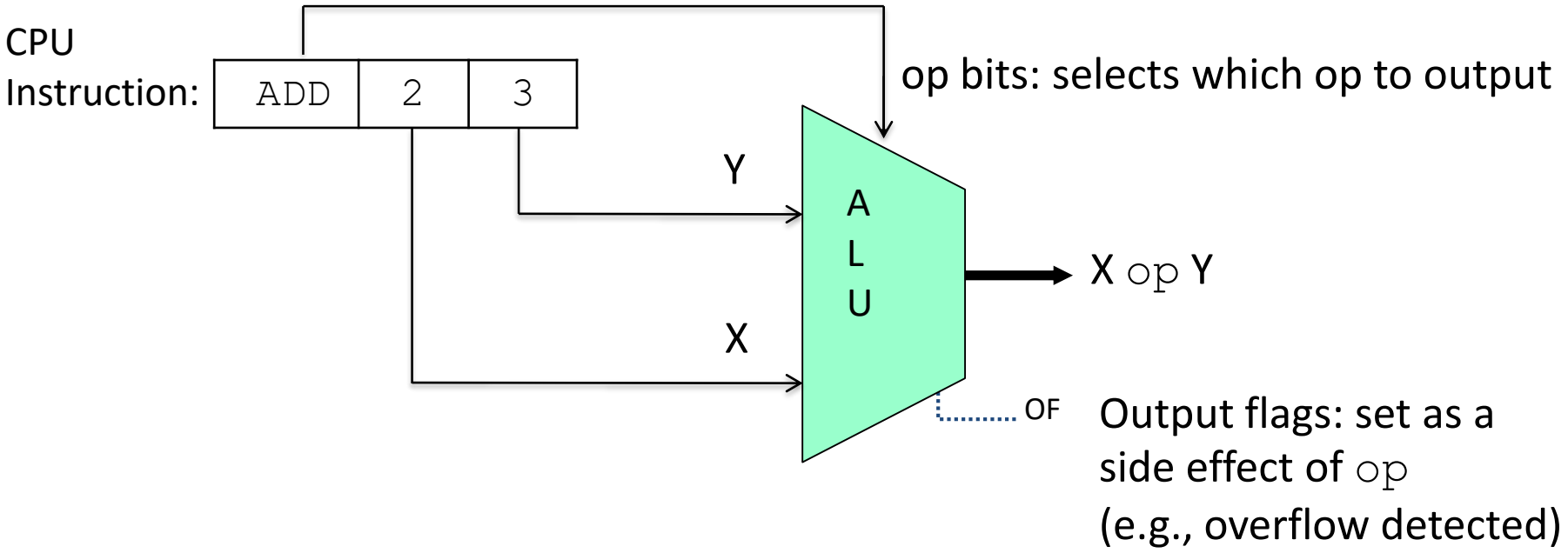
c1	c0	output
0	0	D0
0	1	D1
1	0	D2
1	1	D3



Simple 3-bit ALU: Add and bitwise OR



ALU: Arithmetic Logic Unit



- Arithmetic and logic circuits: ADD, SUB, NOT, …
- Control circuits: use op bits to select output
- Circuits around ALU:
  - Select input values X and Y from instruction or register
  - Select op bits from instruction to feed into ALU
  - Feed output somewhere

Digital Circuits - Building a CPU

Three main classifications of HW circuits:

1. ALU: implement arithmetic & logic functionality

   (ex) adder to add two values together

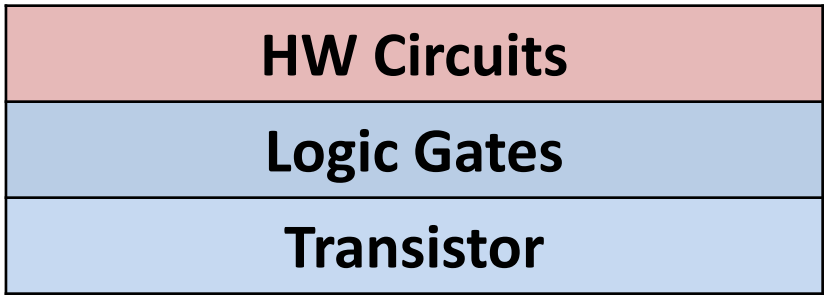
2. Storage: to store binary values

   (ex) Register File: set of CPU registers

3. Control: support/coordinate instruction execution

   (ex) fetch the next instruction to execute

Circuits are built from Logic Gates which are built from transistors



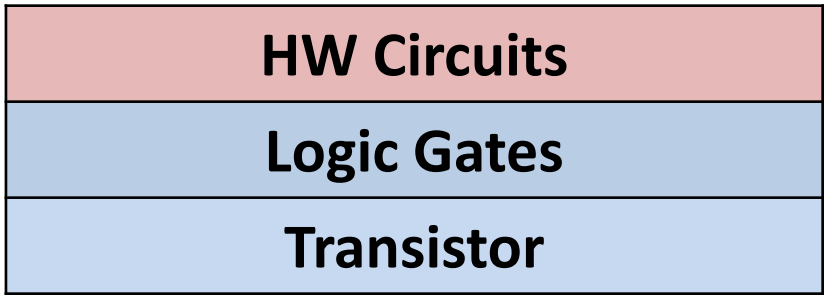
Digital Circuits - Building a CPU

Three main classifications of HW circuits:

2. Storage: to store binary values

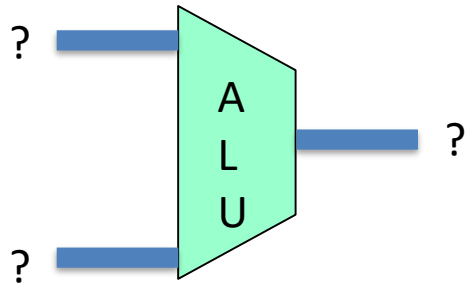
   (ex) Register File: set of CPU registers

Give the CPU a “scratch space” to perform calculations and keep track of the state its in.



CPU so far…

- We can perform arithmetic!
- Storage questions:
  - Where to the ALU input values come from?
  - Where do we store the result?
  - What does this “register” thing mean?



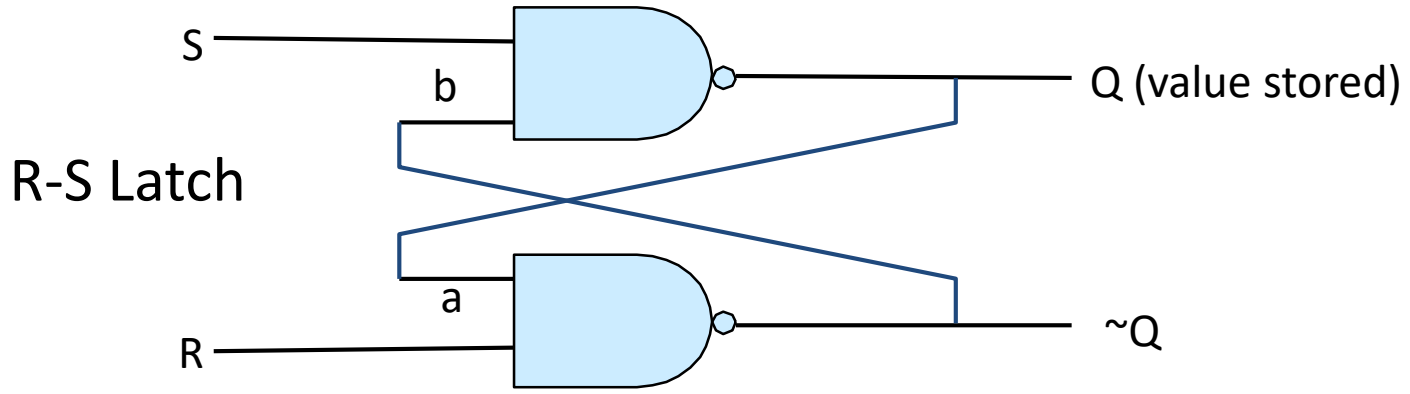
Memory Circuit Goals: Starting Small

- Store a 0 or 1
- Retrieve the 0 or 1 value on demand (read)
- Set the 0 or 1 value on demand (write)

R-S Latch: Stores Value Q

When R and S are both 1: Maintain a value

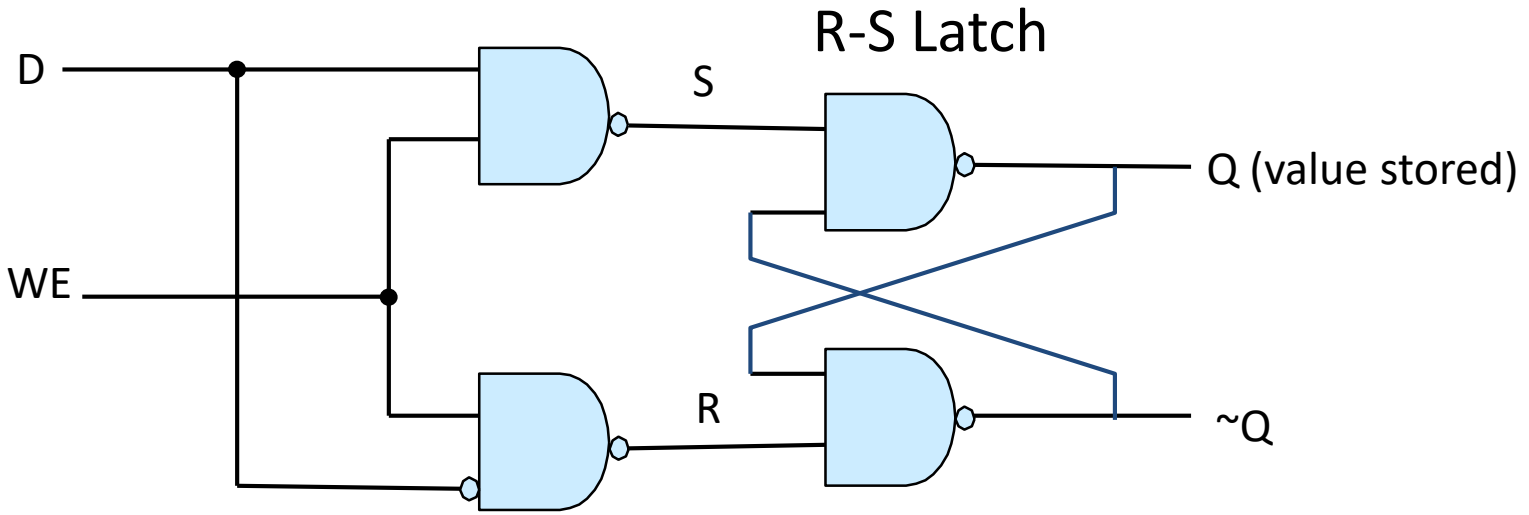
R and S are never both simultaneously 0



- To write a new value:
  - Set S to 0 momentarily (R stays at 1): to write a 1
  - Set R to 0 momentarily (S stays at 1): to write a 0

Gated D Latch

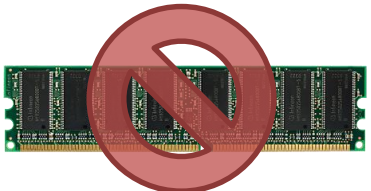
Controls S-R latch writing, ensures S & R never both 0



D: into top NAND, ~D into bottom NAND
WE: write-enabled, when set, latch is set to value of D

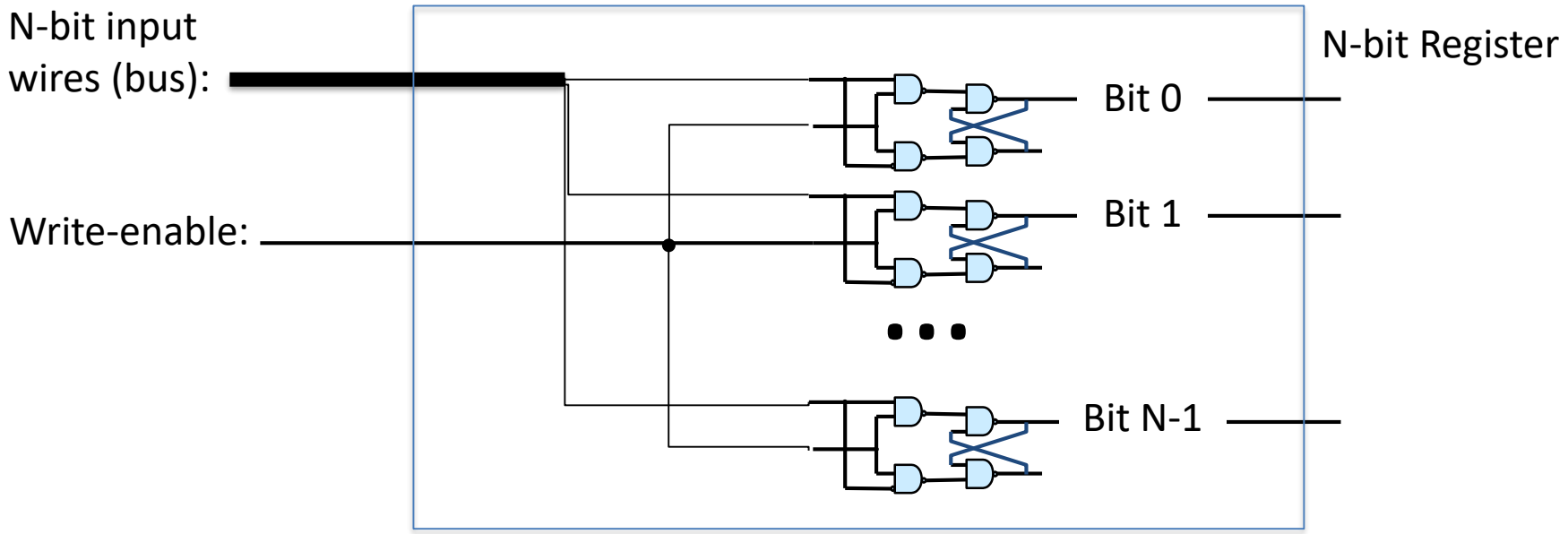
Latches used in registers (up next) and SRAM (caches, later)
Fast, not very dense, expensive

DRAM: capacitor-based:



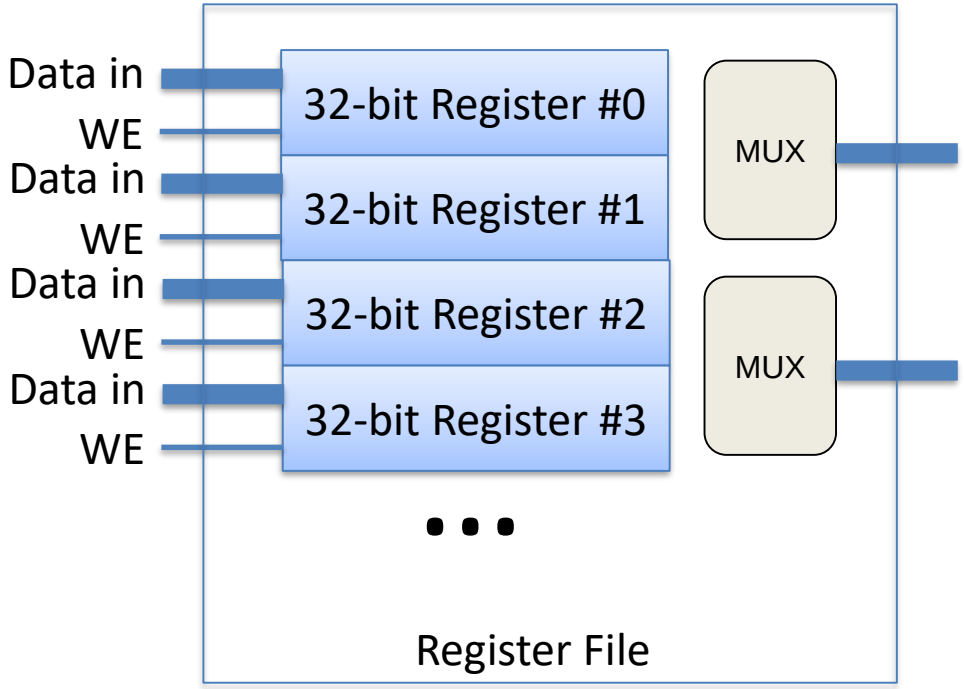
Registers

- Fixed-size storage (8-bit, 32-bit, etc.)
- Gated D latch lets us store one bit
  - Connect N of them to the same write-enable wire!



“Register file”

- A set of registers for the CPU to store temporary values.
- This is (finally) something you will interact with!



- Instructions of form:
  - “add R1 + R2, store result in R3”

Memory Circuit Summary

- Lots of abstraction going on here!
  - Gates hide the details of transistors.
  - Build R-S Latches out of gates to store one bit.
  - Combining multiple latches gives us N-bit register.
  - Grouping N-bit registers gives us register file.

- Register file's simple interface:
  - Read R_x's value, use for calculation
  - Write R_y's value to store result

Digital Circuits - Building a CPU

Three main classifications of HW circuits:

1. ALU: implement arithmetic & logic functionality

   (ex) adder to add two values together

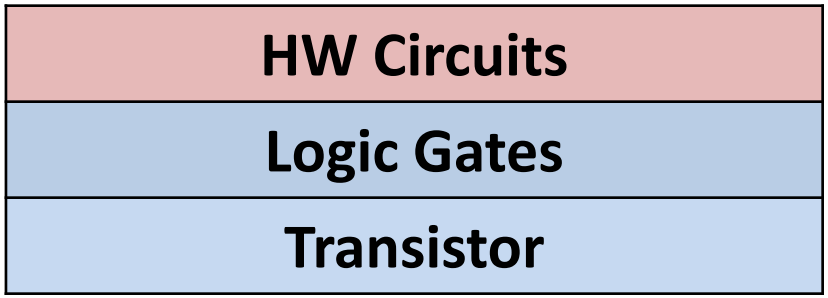
2. Storage: to store binary values

   (ex) Register File: set of CPU registers

3. Control: support/coordinate instruction execution

   (ex) fetch the next instruction to execute

Circuits are built from Logic Gates which are built from transistors



Digital Circuits - Building a CPU

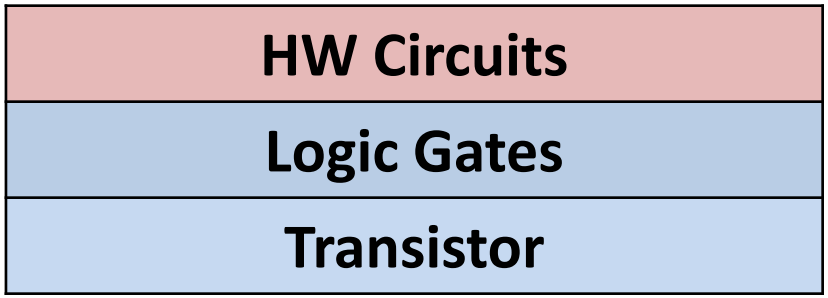
Three main classifications of HW circuits:

3. Control: support/coordinate instruction execution

   (ex) fetch the next instruction to execute

Keep track of where we are in the program.

Execute instruction, move to next.



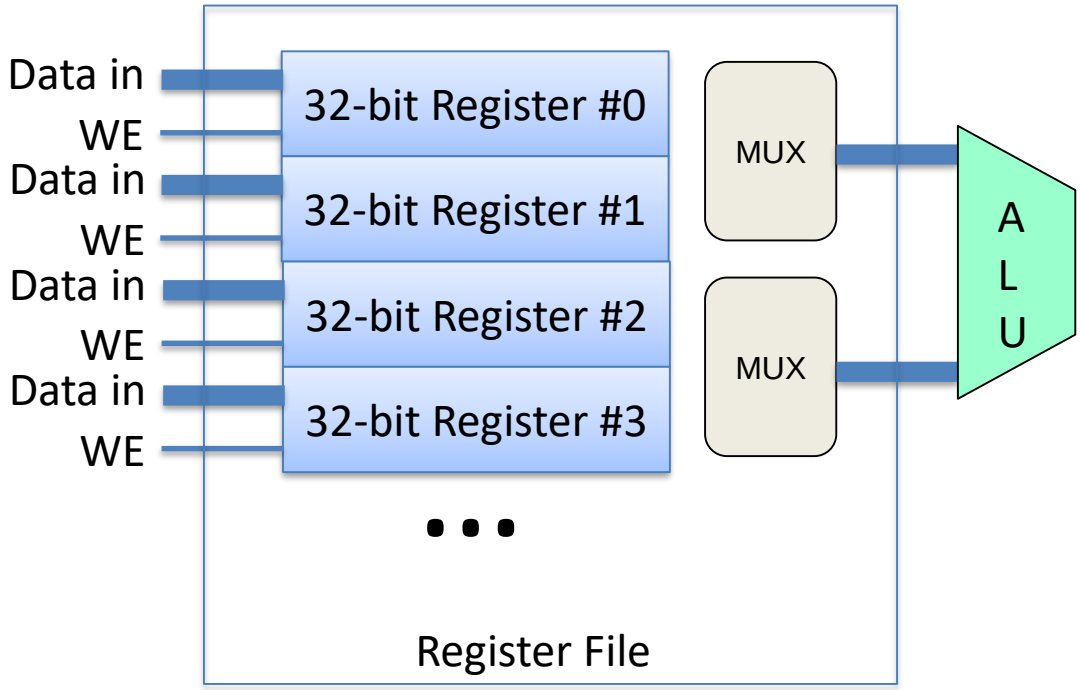
CPU so far…

We know how to store data (in register file).
We know how to perform arithmetic on it, by feeding it to ALU.

Remaining questions:

- Which register(s) do we use as input to ALU?
- Which operation should the ALU perform?
- To which register should we store the result?

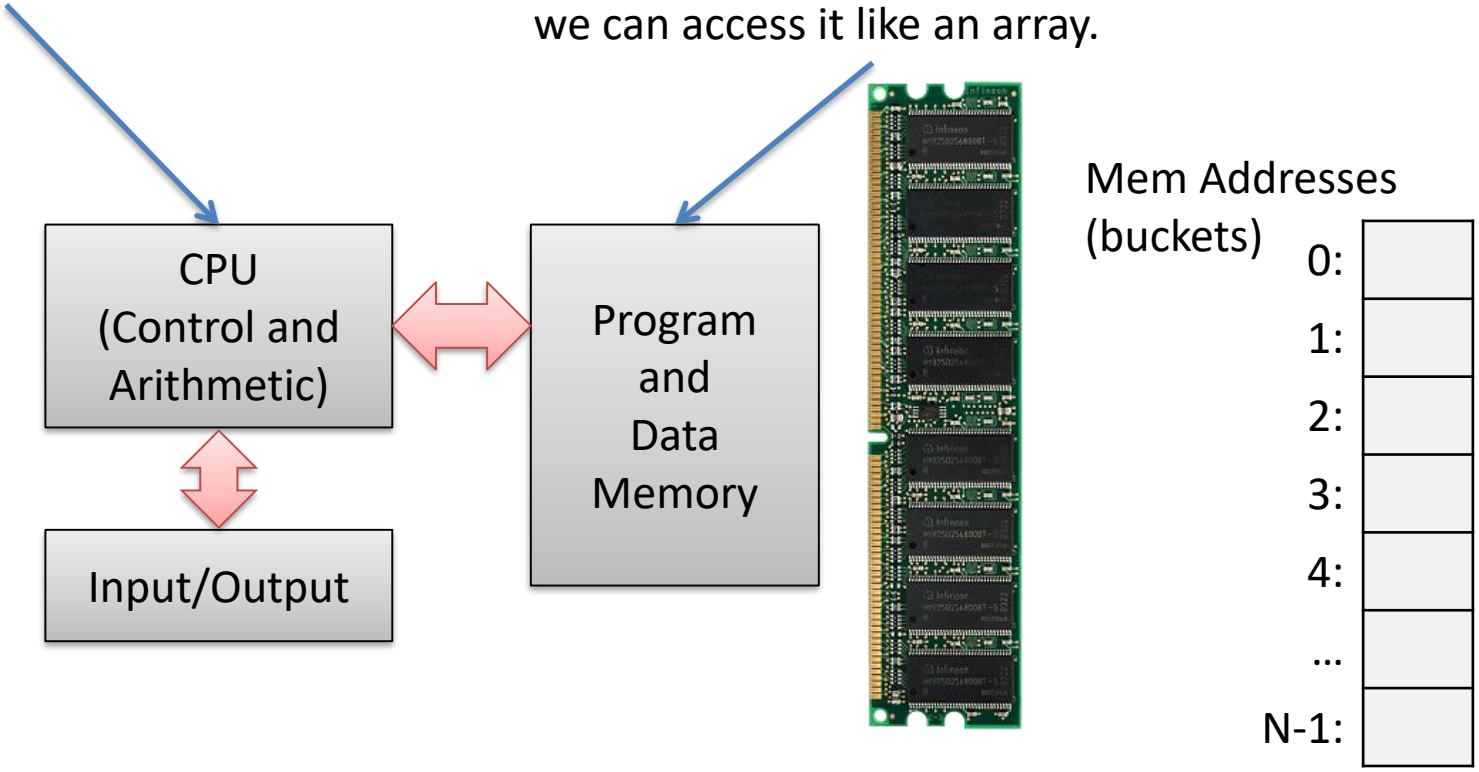
All this info comes from our program:
a series of instructions.



Recall: Von Neumann Model

We're building this.

Our program (instructions) live here. We'll assume for now that we can access it like an array.



CPU Game Plan

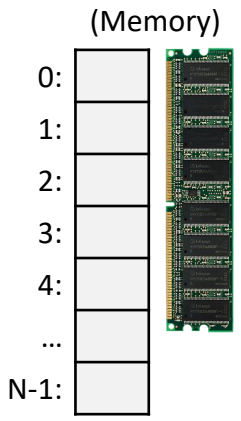
- Fetch instruction from memory
- Decode what the instruction is telling us to do
  - Tell the ALU what it should be doing
  - Find the correct operands
- Execute the instruction (arithmetic, etc.)
- Store the result

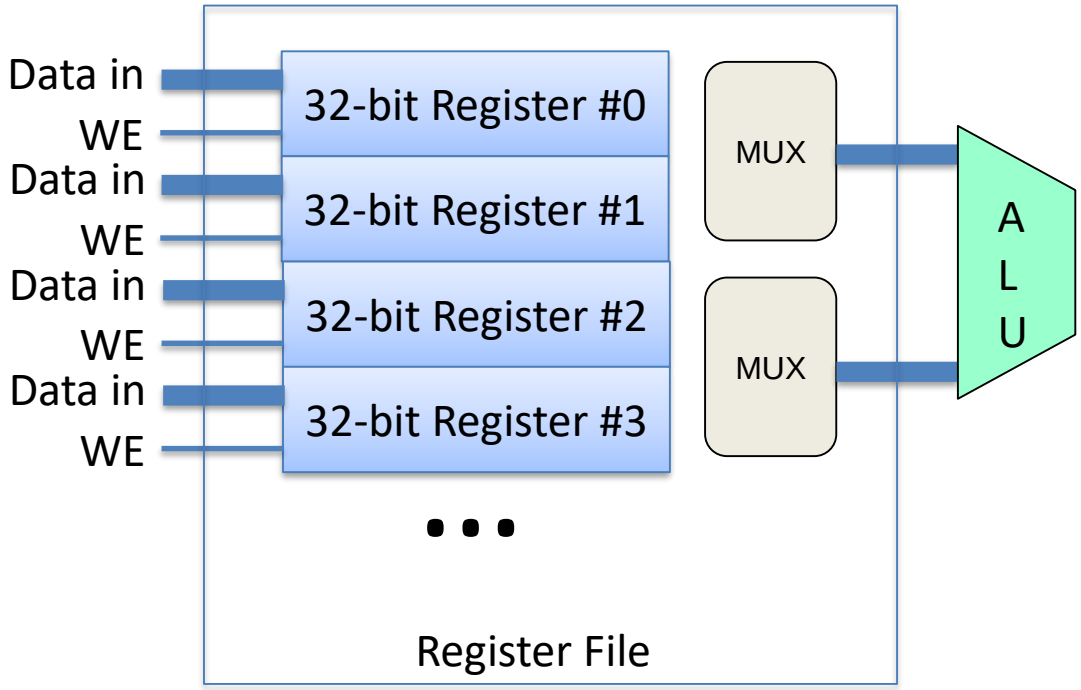
Program State

Let's add two more special registers (not in register file) to keep track of program.

Program Counter (PC): **Memory address of next instr**

Instruction Register (IR): **Instruction contents (bits)**



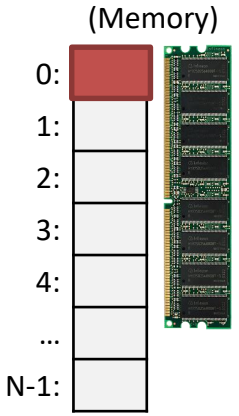


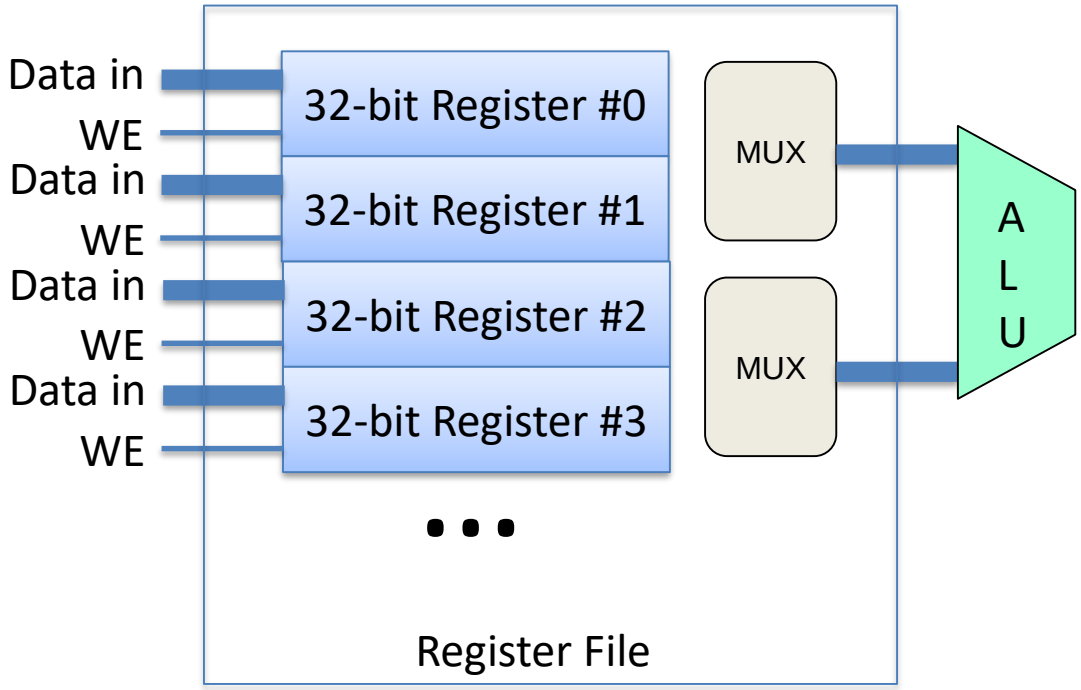
Fetching instructions.

Load IR with the contents of memory at the address stored in the PC.

Program Counter (PC): **Address 0**

Instruction Register (IR): Instruction at Address 0



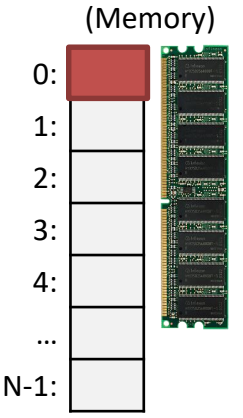


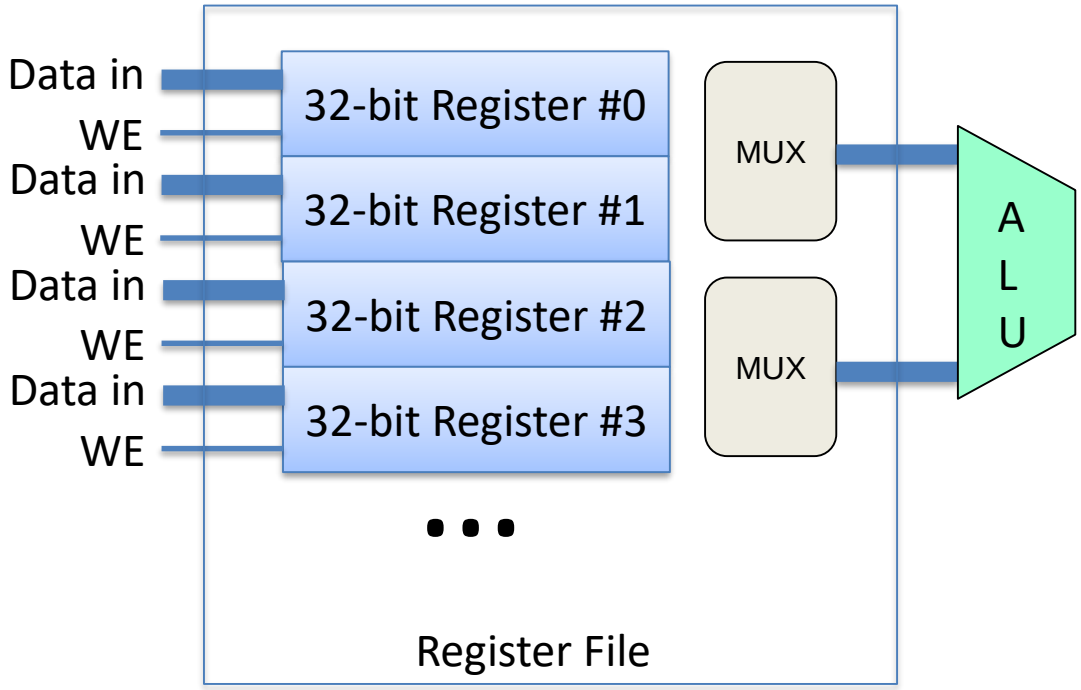
Decoding instructions.

Interpret the instruction bits: What operation? Which arguments?

Program Counter (PC): **Address 0**

Instruction Register (IR): OP Code | Reg A | Reg B | Result





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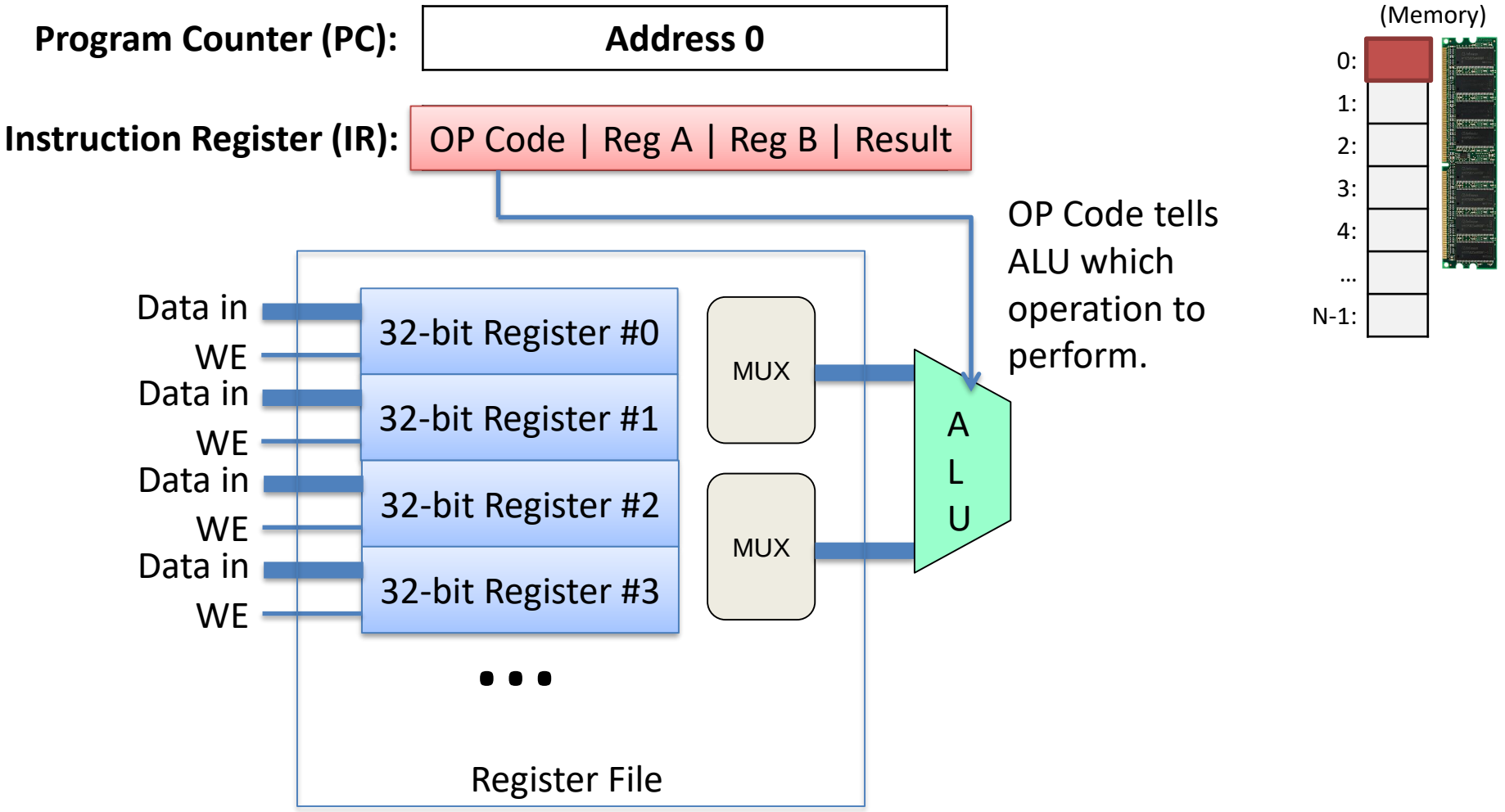

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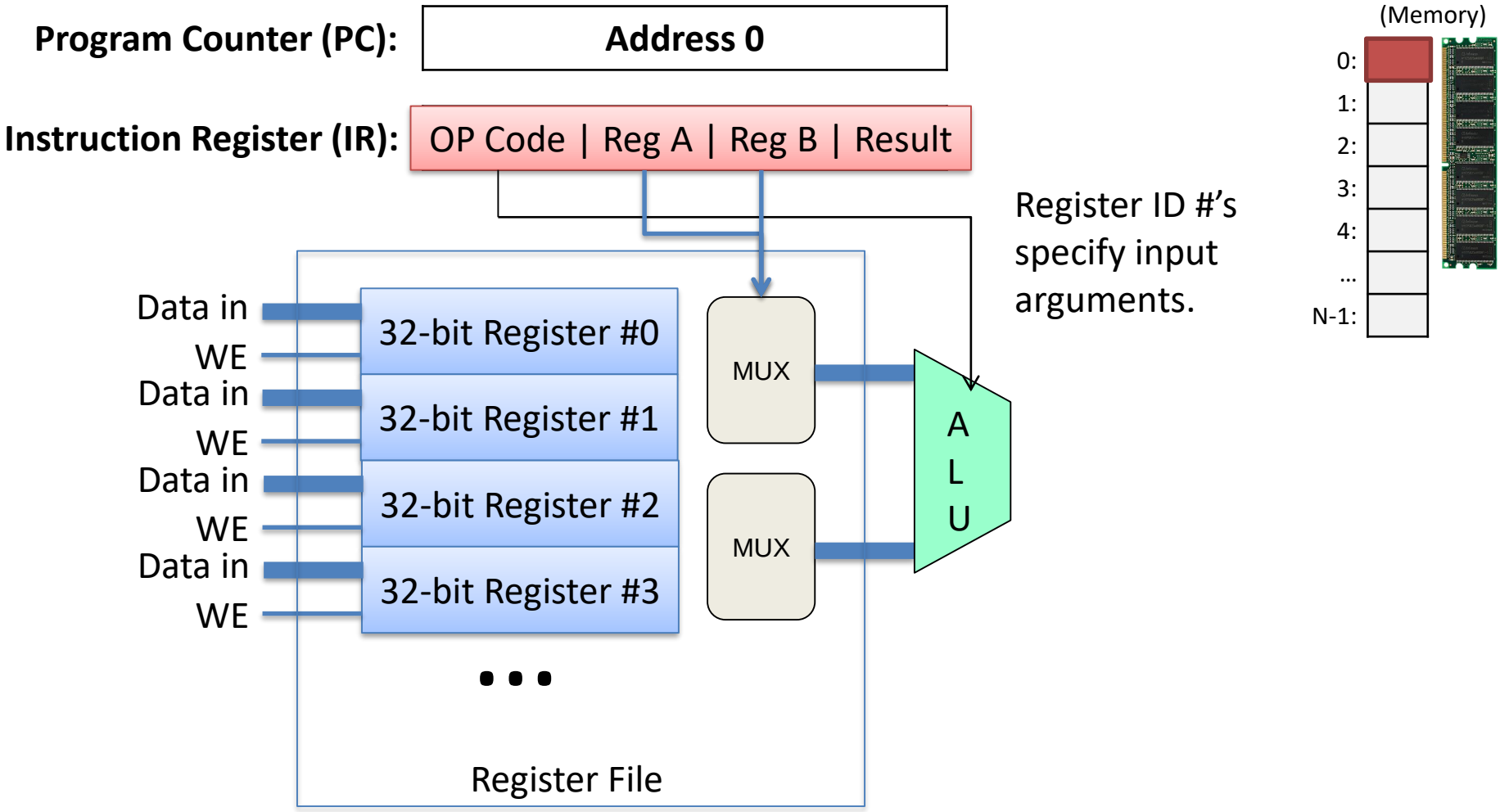
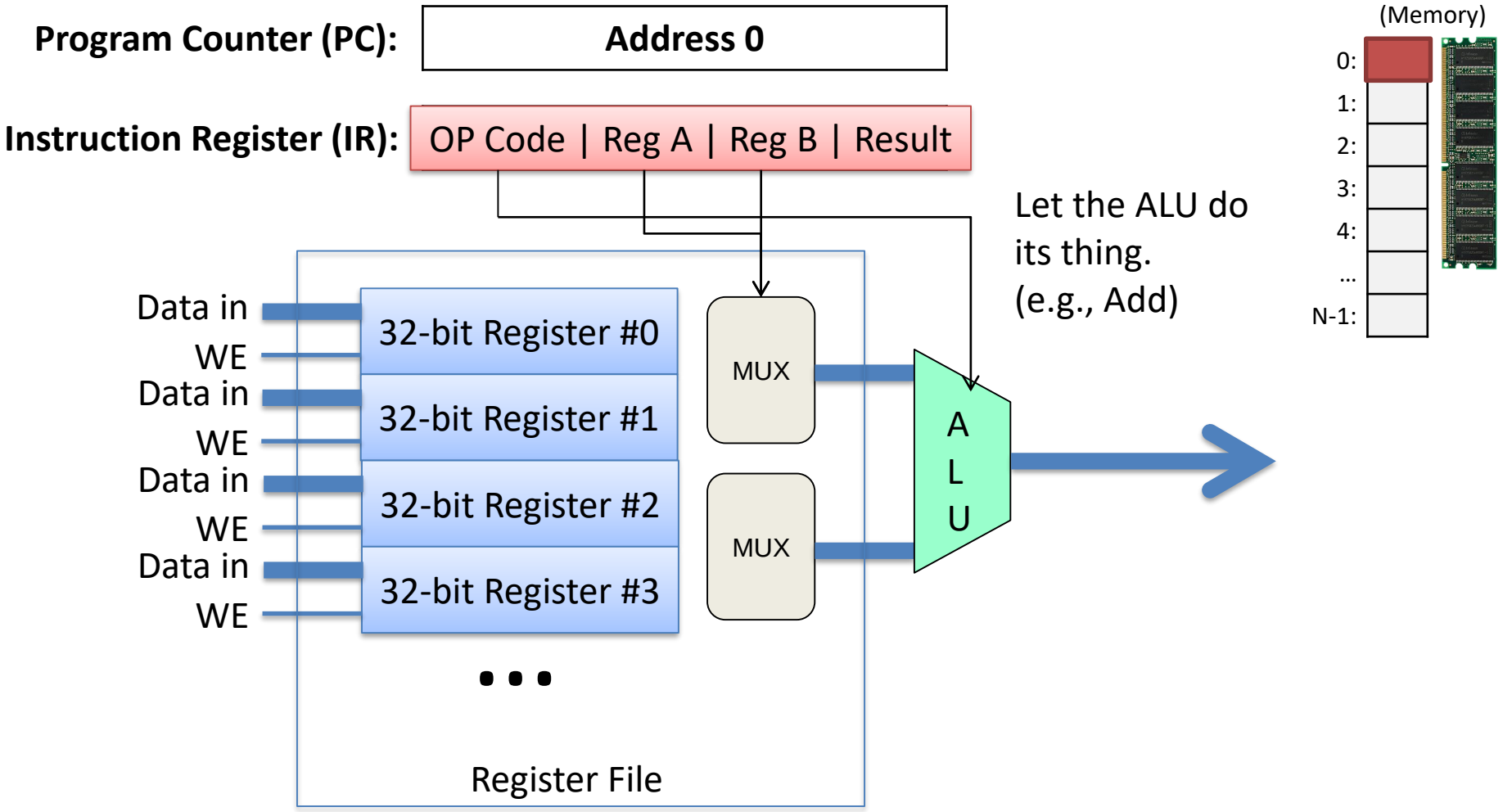


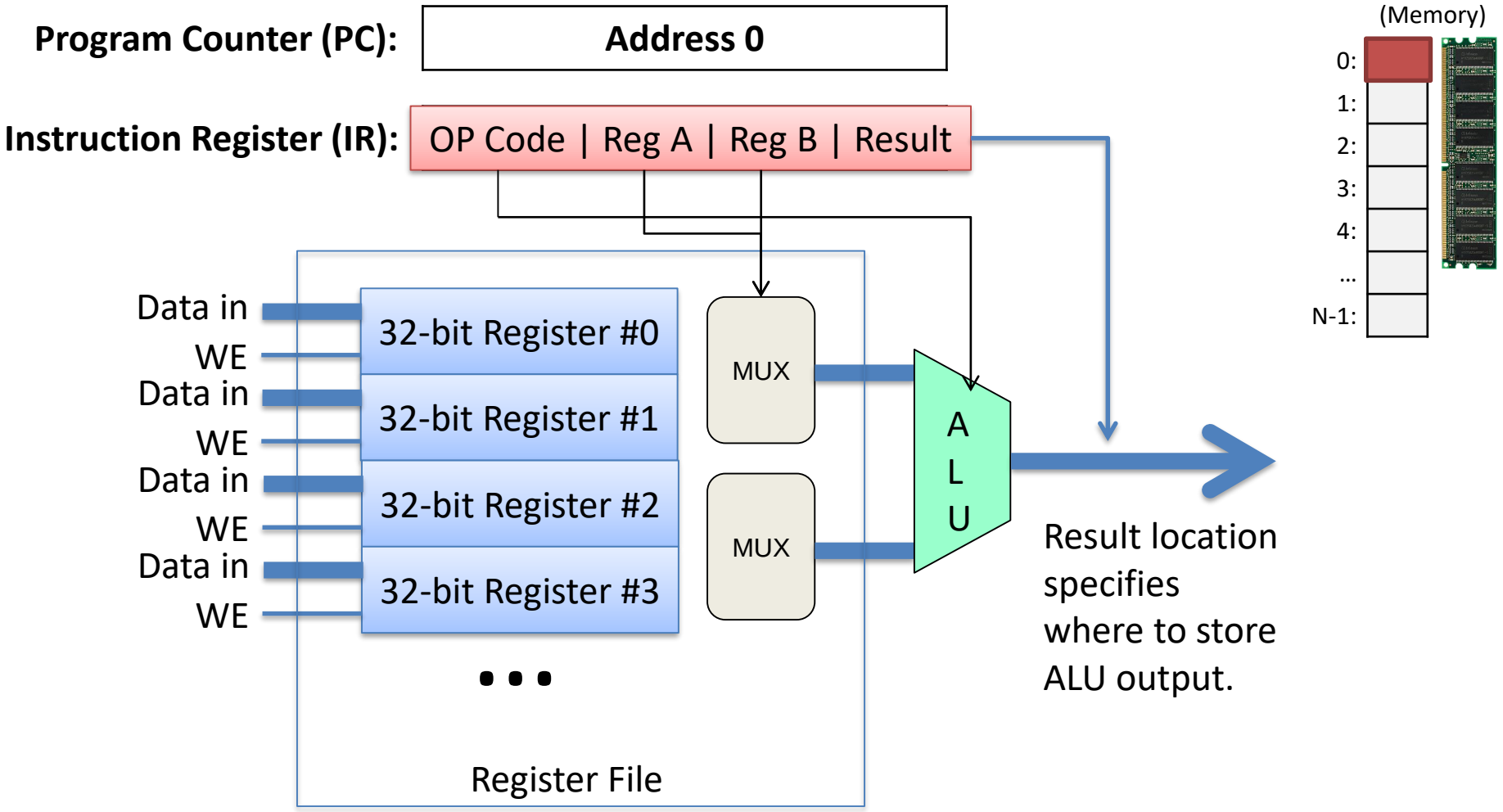
Executing instructions.

Interpret the instruction bits: What operation? Which arguments?



Storing results.

We've just computed something. Where do we put it?

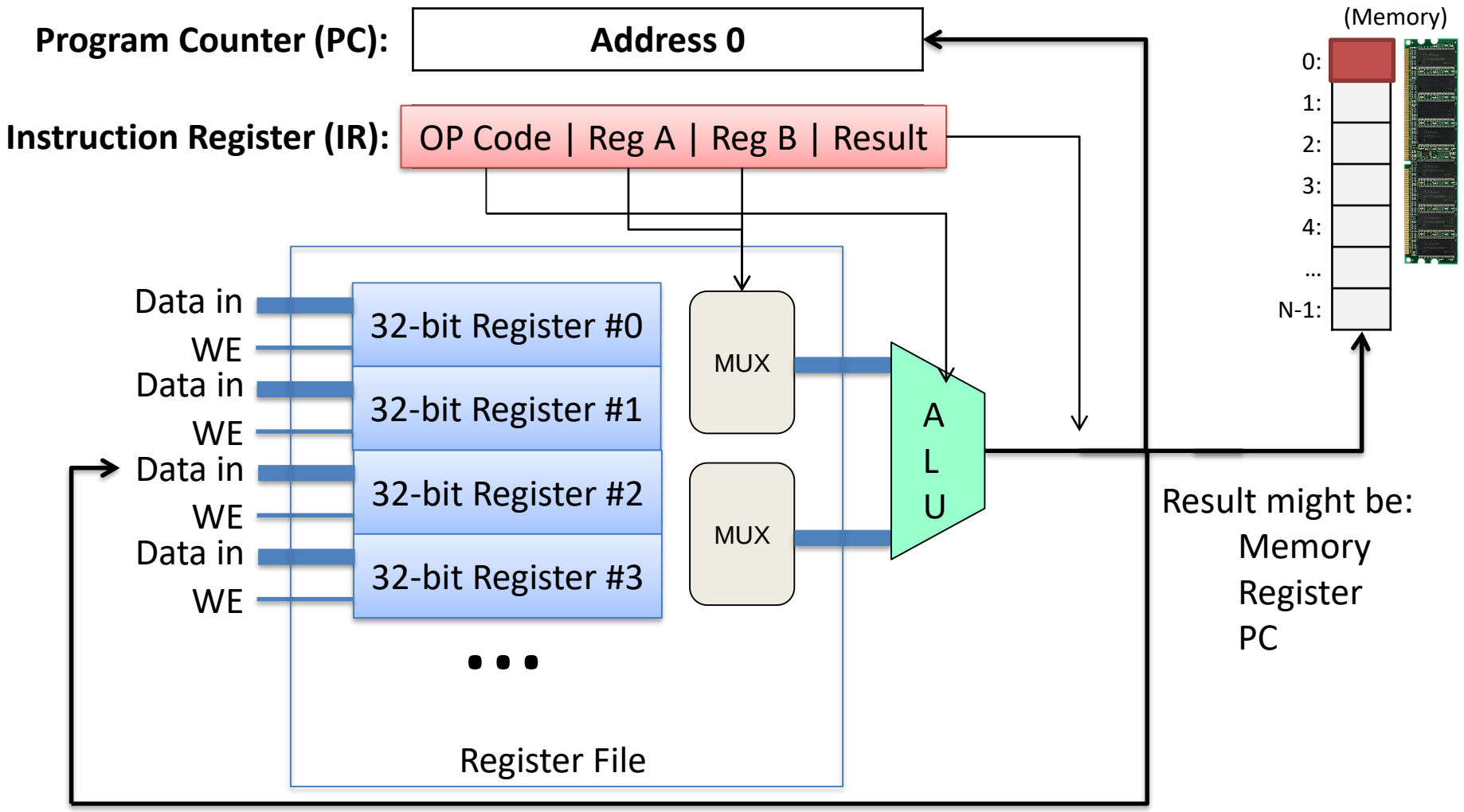


Why do we need a program counter? Can't we just start at 0 and count up one at a time from there?

A. We don't, it's there for convenience.
B. Some instructions might skip the PC forward by more than one.
C. Some instructions might adjust the PC backwards.
D. We need the PC for some other reason(s).

Storing results.

Interpret the instruction bits: What operation? Which arguments?

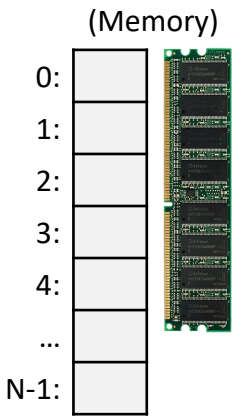


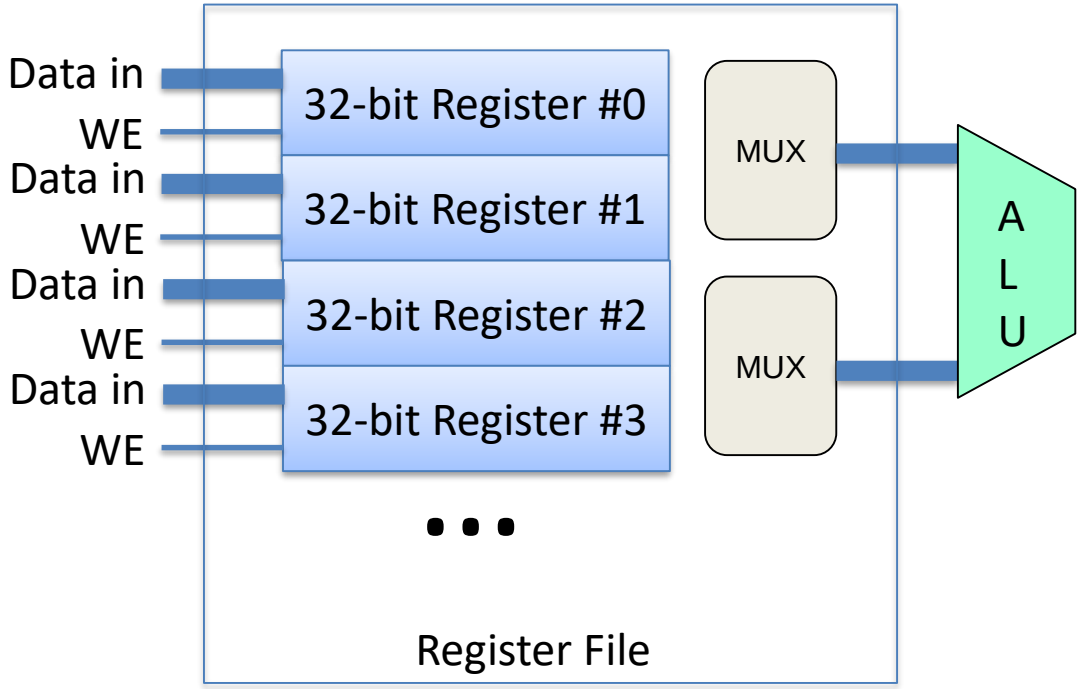
Recap CPU Model

Four stages: fetch instruction, decode instruction, execute, store result

Program Counter (PC): **Memory address of next instr**

Instruction Register (IR): **Instruction contents (bits)**



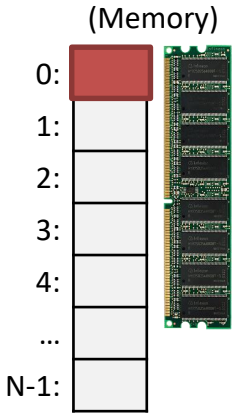


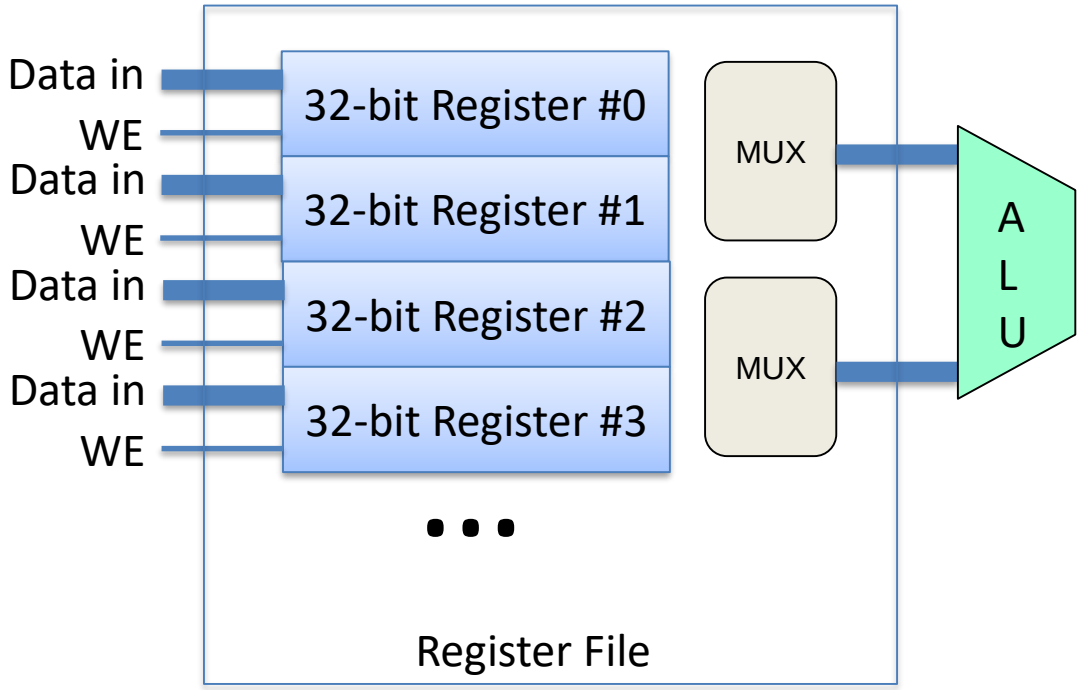
Fetching instructions.

Load IR with the contents of memory at the address stored in the PC.

Program Counter (PC): **Address 0**

Instruction Register (IR): Instruction at Address 0



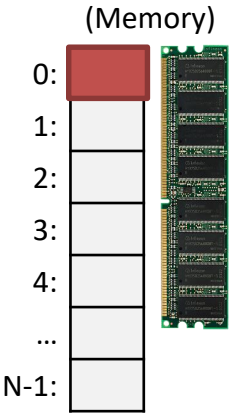


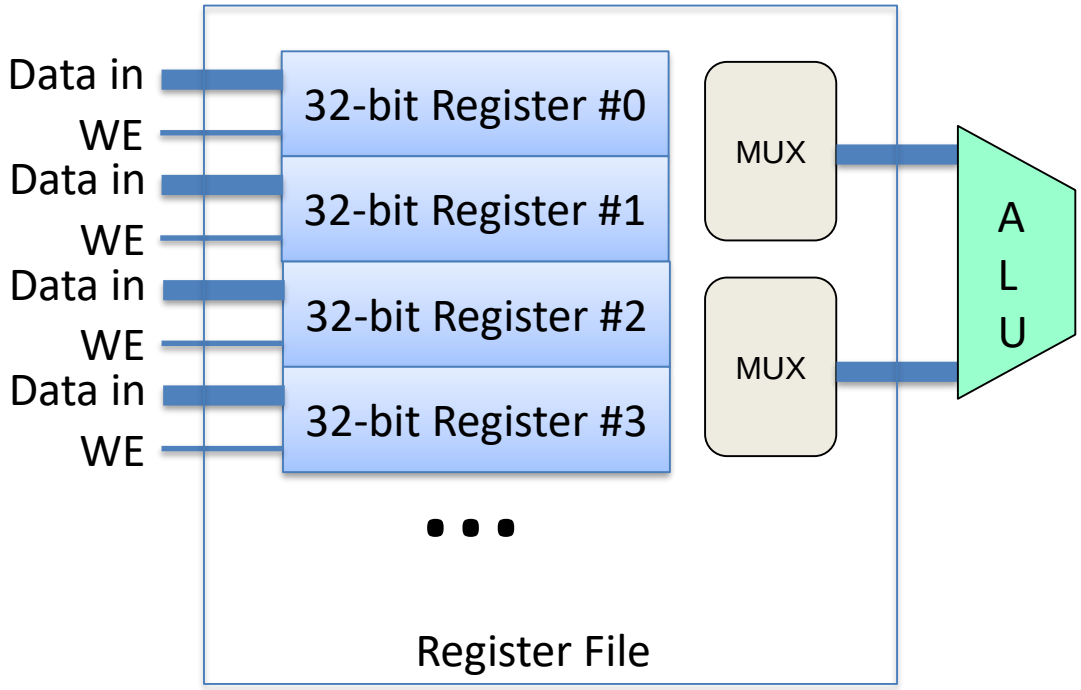
Decoding instructions.

Interpret the instruction bits: What operation? Which arguments?

Program Counter (PC): **Address 0**

Instruction Register (IR): OP Code | Reg A | Reg B | Result





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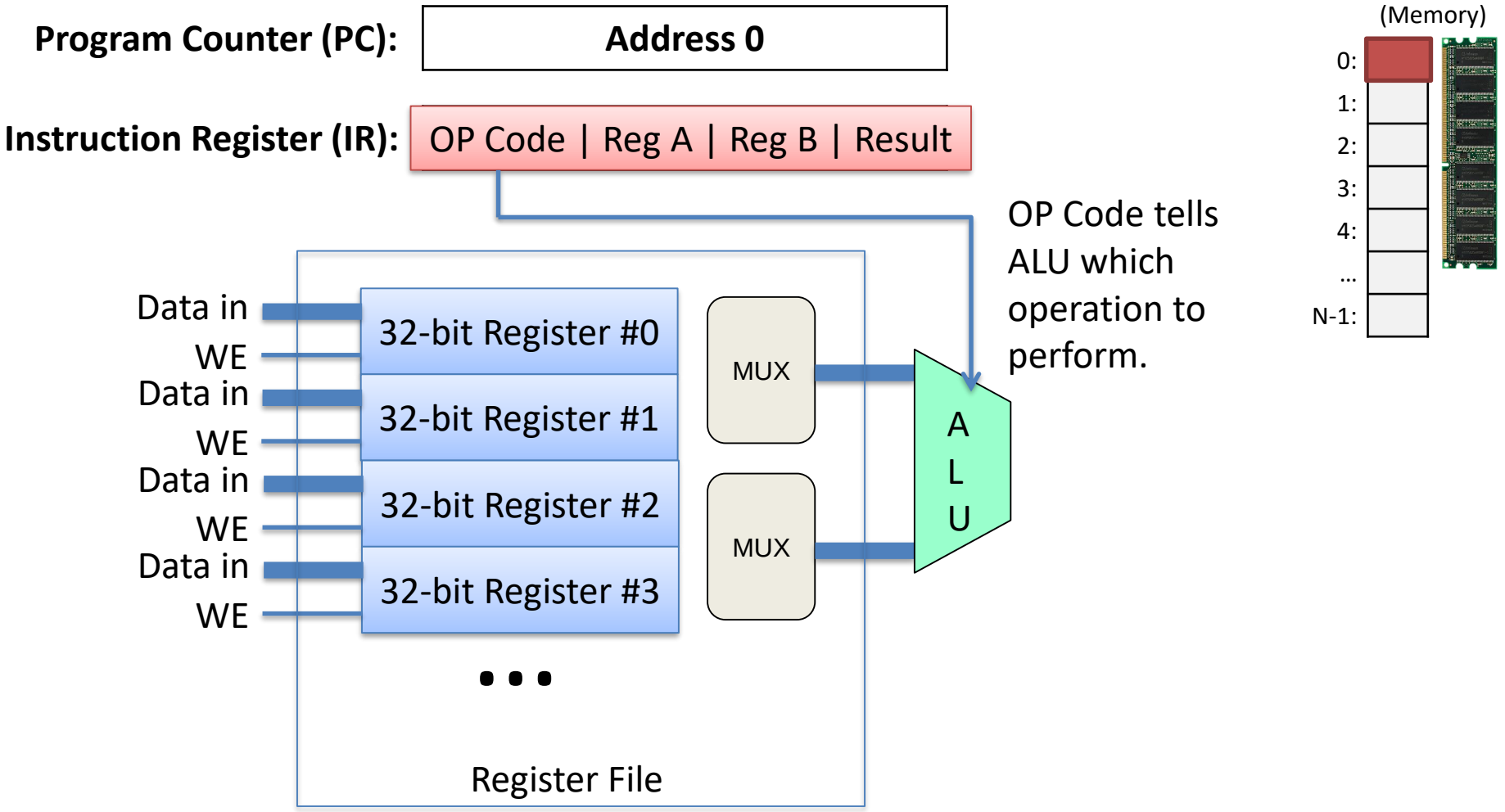

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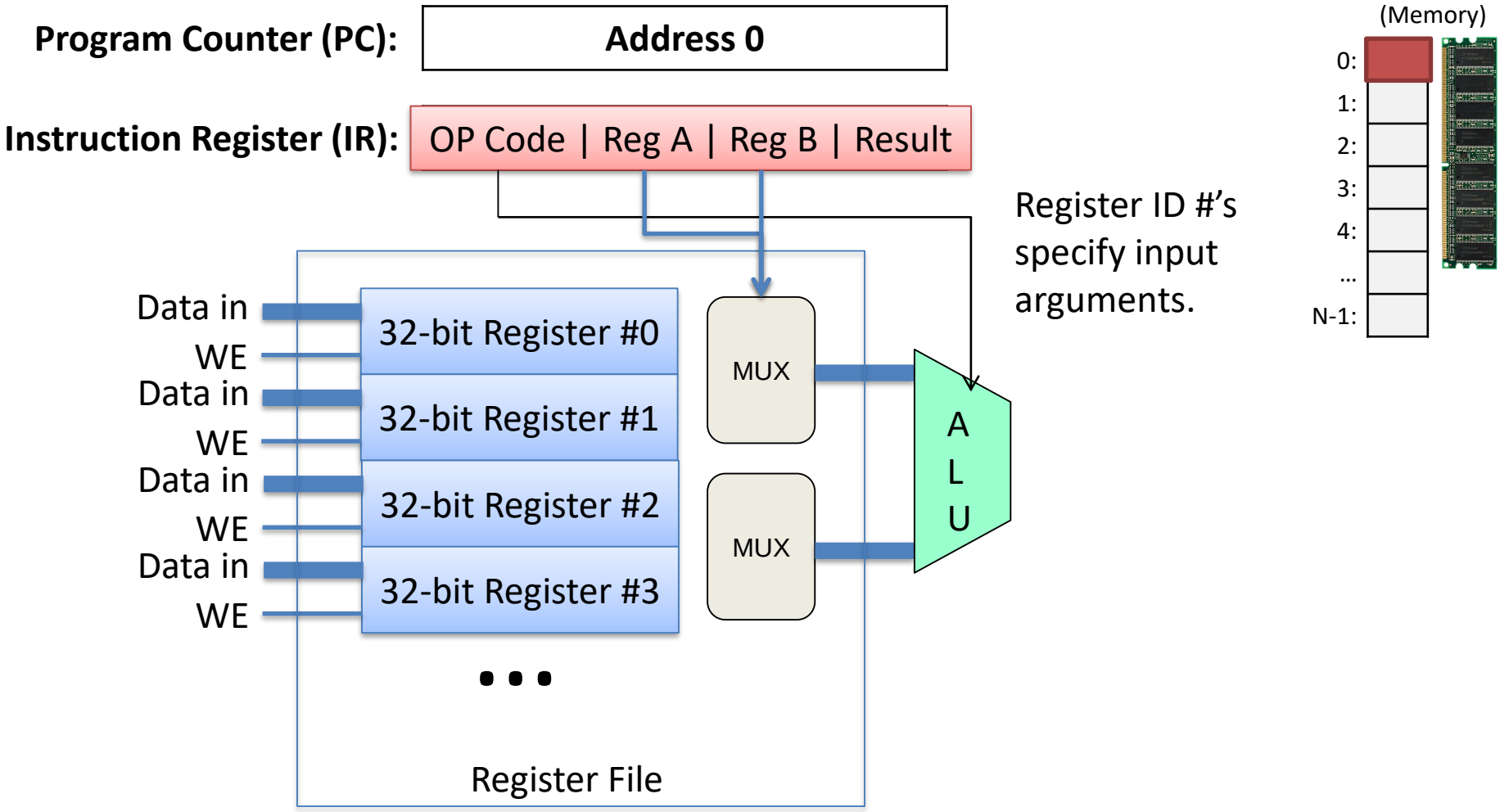
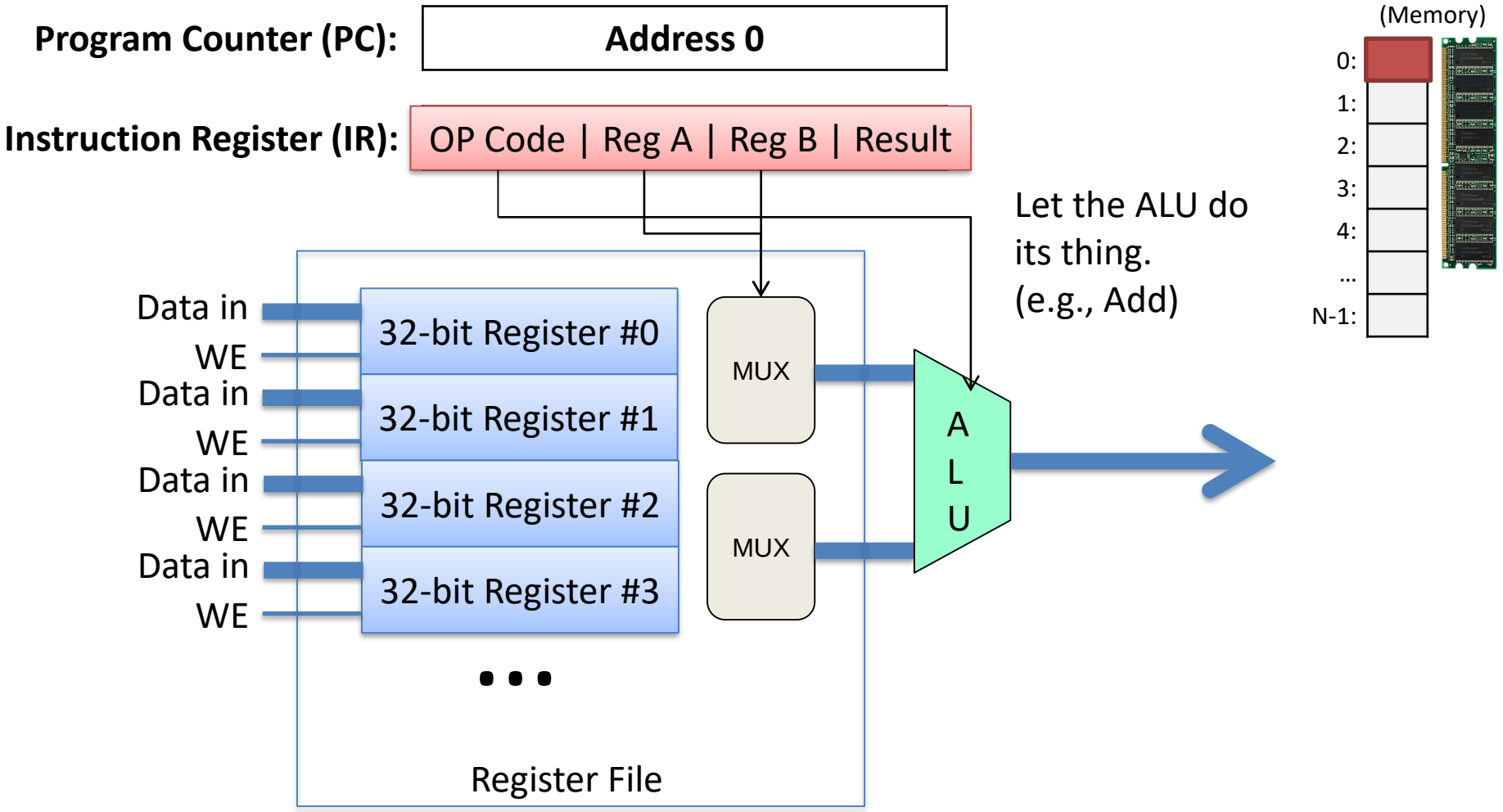


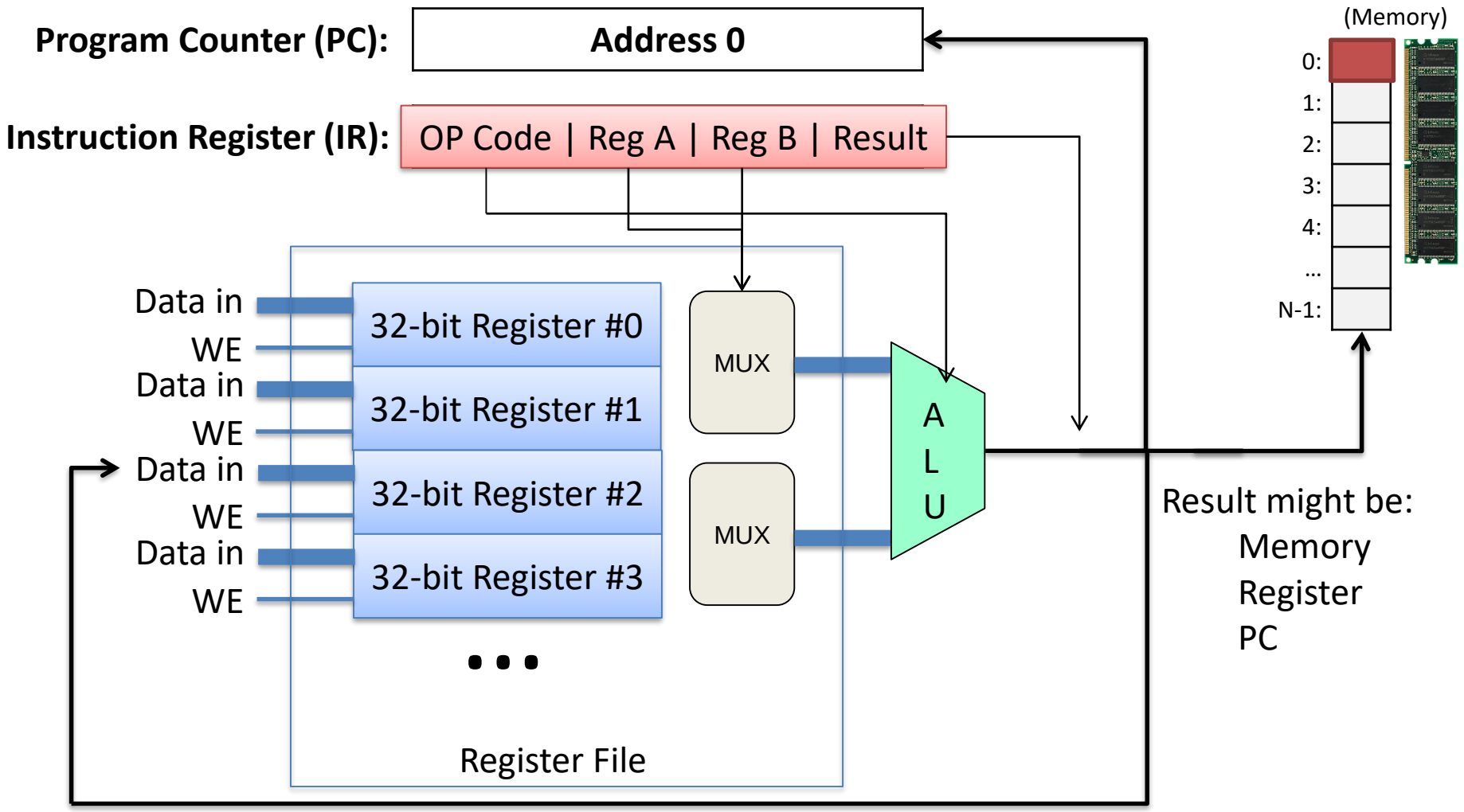
Executing instructions.

Interpret the instruction bits: What operation? Which arguments?



Storing results.

Interpret the instruction bits: Store result in register, memory, PC.



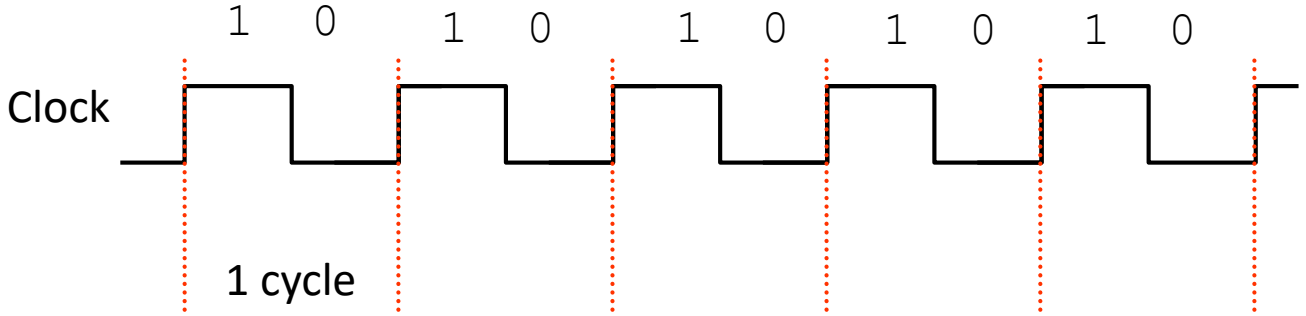
Clocking

- Need to periodically transition from one instruction to the next.

- It takes time to fetch from memory, for signal to propagate through wires, etc.
  - Too fast: don’t fully compute result
  - Too slow: waste time

Clock Driven System

- Everything in is driven by a discrete clock
  - clock: an oscillator circuit, generates hi low pulse
  - clock cycle: one hi-low pair



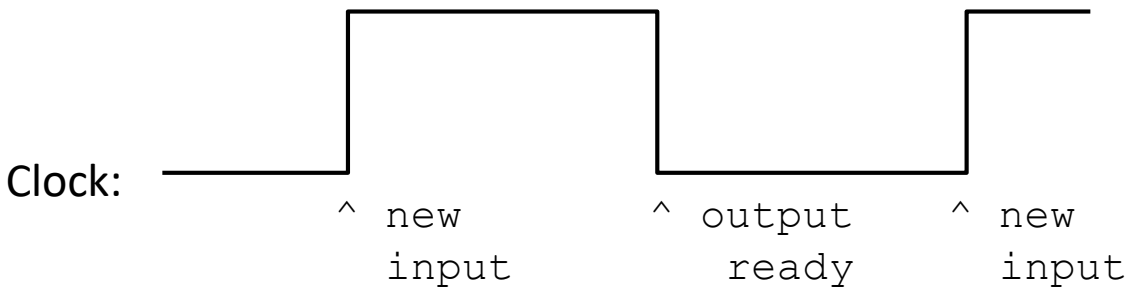
  - Clock determines how fast system runs
    - Processor can only do one thing per clock cycle
      - Usually just one part of executing an instruction
    - 1GHz processor:

      1 billion cycles/second → 1 cycle every nanosecond

Clock and Circuits

Clock Edges Triggers events

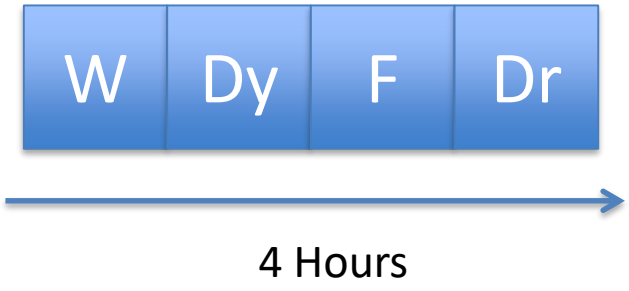
- Circuits have continuous values
- Rising Edge: trigger new input values
- Falling Edge: consistent output ready to read
- Between rising and falling edge can have inconsistent state as new input values flow through circuit



Cycle Time: Laundry Analogy

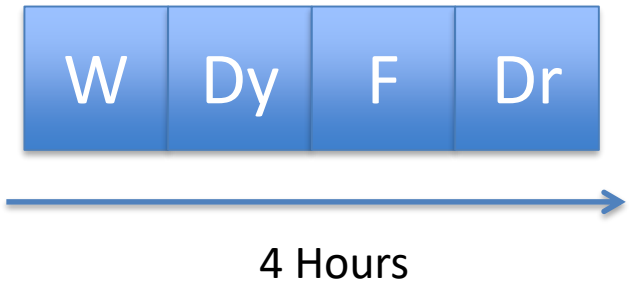
- Discrete stages: fetch, decode, execute, store

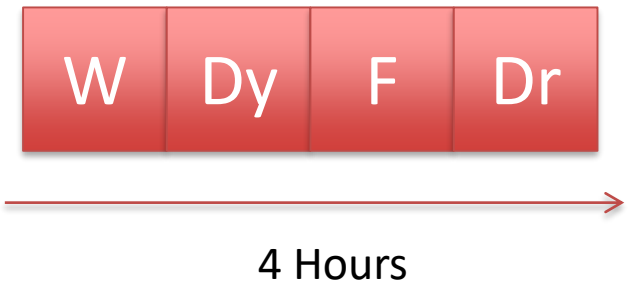
- Analogy (laundry): washer, dryer, folding, dresser

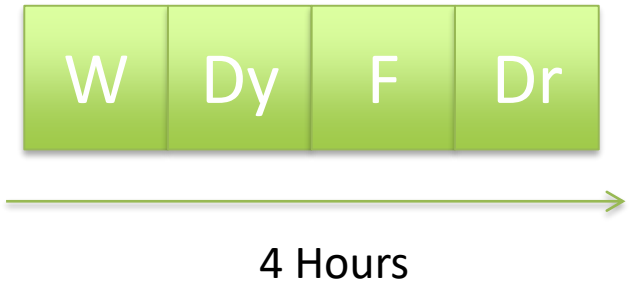


You have big problems if you have millions of loads of laundry to do….

Laundry



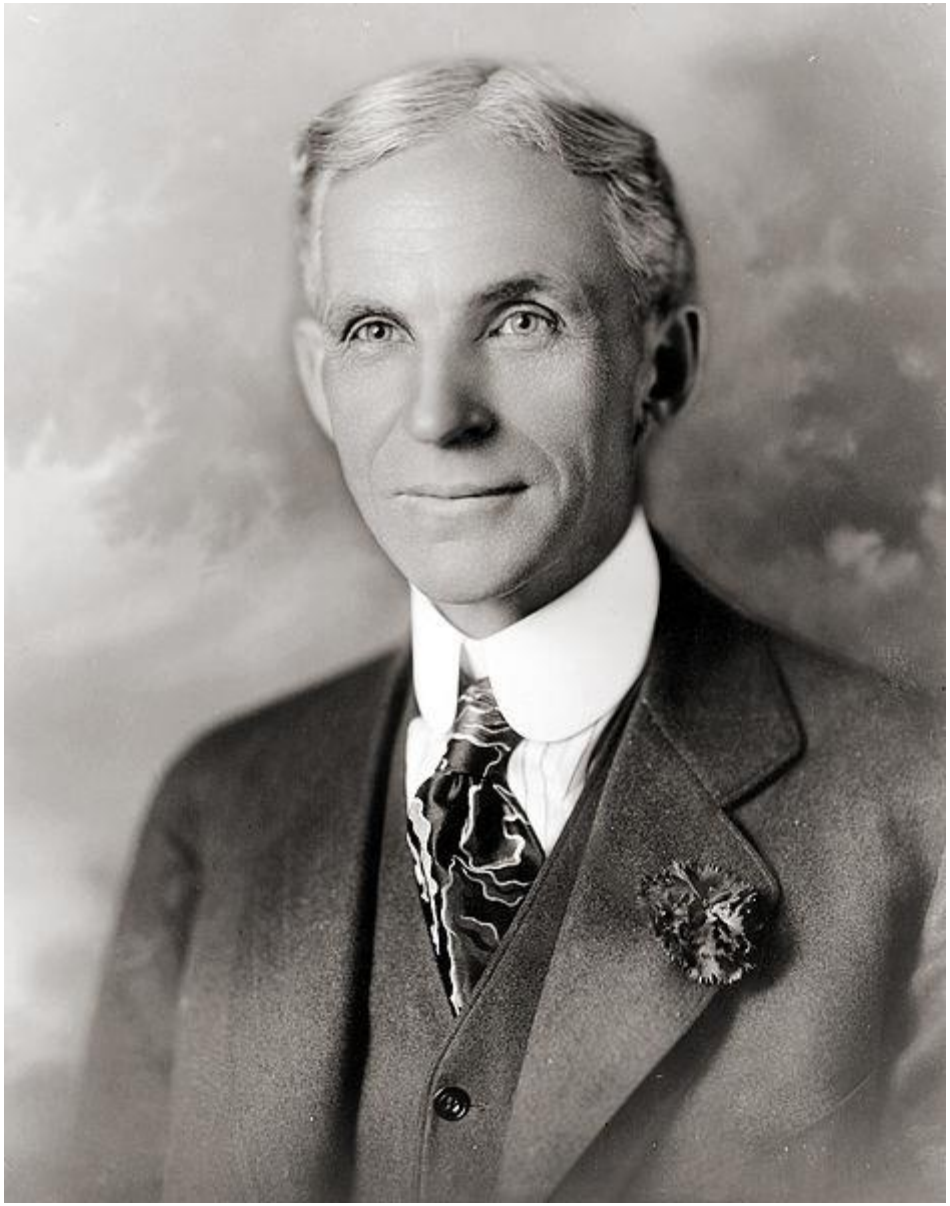




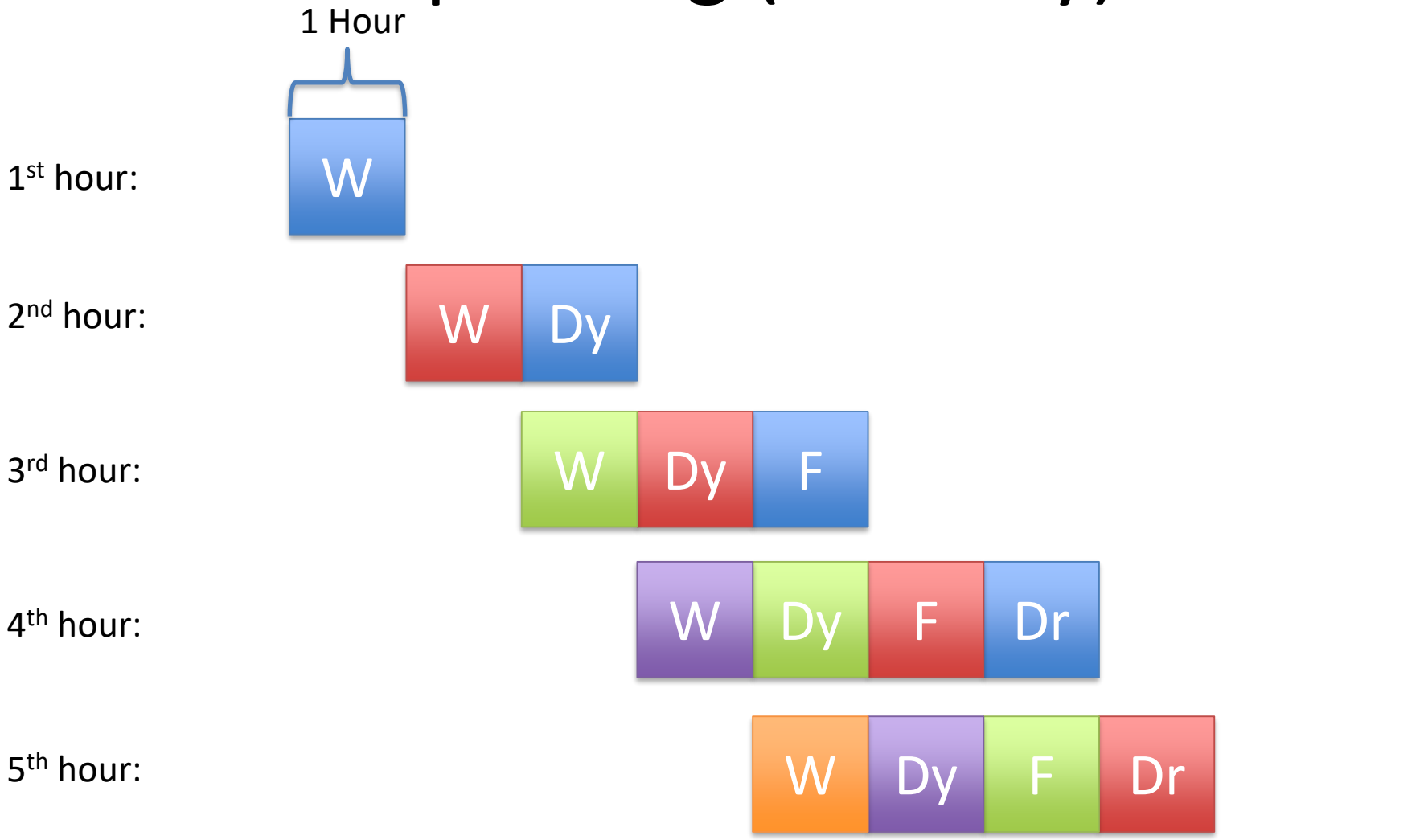
4-hour cycle time.

Finishes a laundry load every cycle.

(6 laundry loads per day)

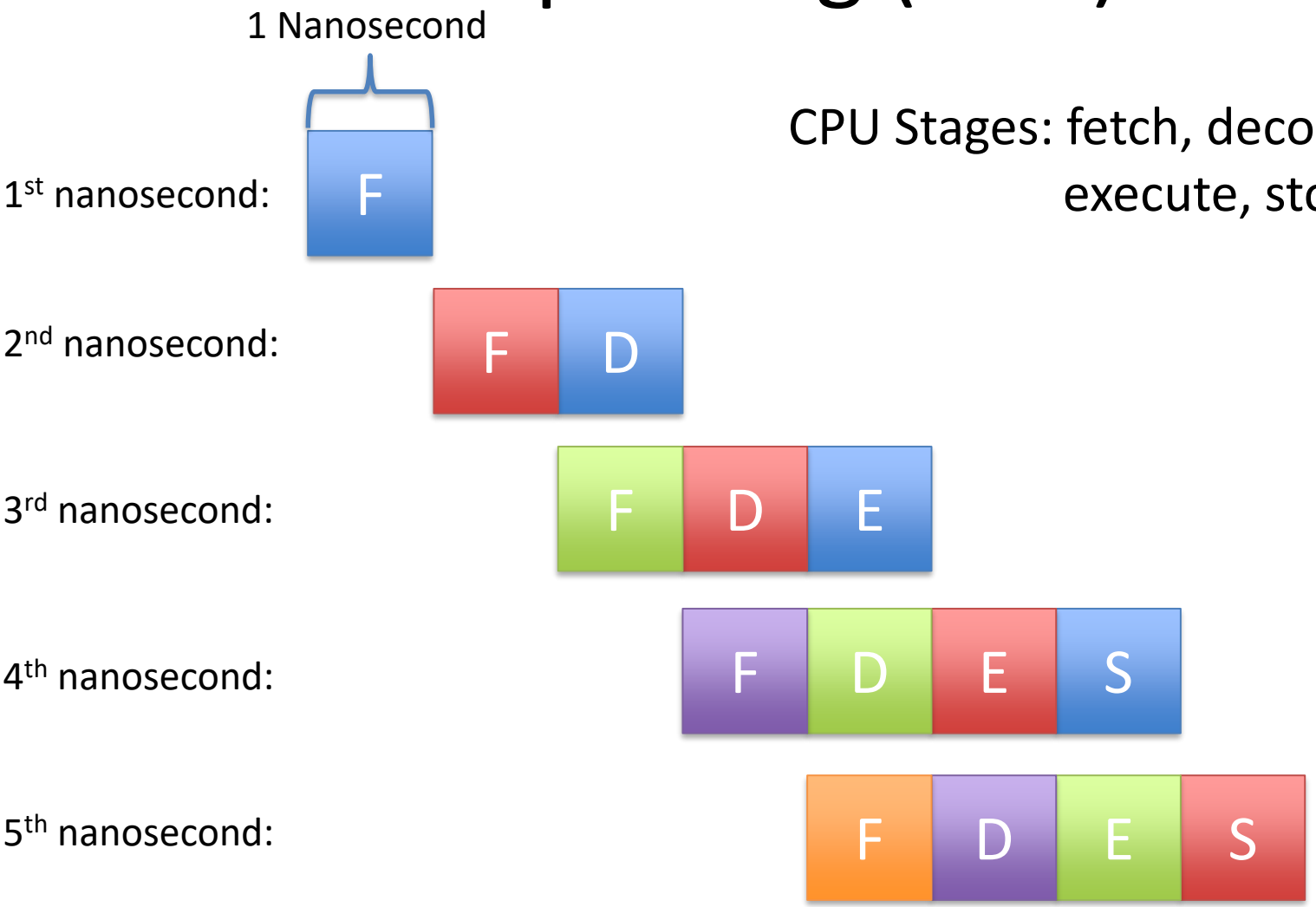


Pipelining (Laundry)



Steady state: One load finishes every hour!
(Not every four hours like before.)

Pipelining (CPU)



CPU Stages: fetch, decode, execute, store results

Steady state: One instruction finishes every nanosecond!
(Clock rate can be faster.)

Pipelining

(For more details about this and the other things we talked about here, take architecture.)

Up next

- Talking to the CPU: Assembly language